

3.5 Properties of continuous-time Fourier series

$x(t) \xleftrightarrow{\mathcal{FS}} a_k$ Fourier Series Pair

with Period T , Fundamental Frequency $\omega_0 = 2\pi/T$

3.5.1 Linearity

$x(t) \xleftrightarrow{\mathcal{FS}} a_k$ $y(t) \xleftrightarrow{\mathcal{FS}} b_k$

$$z(t) = Ax(t) + By(t) \xleftrightarrow{\mathcal{FS}} c_k = Aa_k + Bb_k$$

Proof) $c_k = \frac{1}{T} \int_T z(t) e^{-jk\omega_0 t} dt = \frac{1}{T} \int_T [Ax(t) + By(t)] e^{-jk\omega_0 t} dt$

$$= A \left(\frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt \right) + B \left(\frac{1}{T} \int_T y(t) e^{-jk\omega_0 t} dt \right)$$
$$= Aa_k + Bb_k$$



3.5.2 Time shifting

$x(t - t_0)$ Time Shift

$$\begin{aligned} b_k &= \frac{1}{T} \int_T x(t - t_0) e^{-jk\omega_0 t} dt \\ &= \frac{1}{T} \int_T x(\tau) e^{-jk\omega_0 (\tau + t_0)} d\tau \\ &= e^{-jk\omega_0 t_0} \frac{1}{T} \int_T x(\tau) e^{-jk\omega_0 \tau} d\tau \\ &= e^{-jk\omega_0 t_0} a_k = e^{-jk(2\pi/T)t_0} a_k \end{aligned}$$



3.5.3 Time reversal

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{+\infty} a_k e^{jk(2\pi/T)t}, \text{ then}$$

$$x(-t) = \sum_{k=-\infty}^{\infty} a_k e^{-jk2\pi t/T} \quad y(t) = x(-t) = \sum_{m=-\infty}^{\infty} a_{-m} e^{jm2\pi t/T}$$

$m = -k$

$$= \sum_{m=-\infty}^{\infty} b_m e^{jm2\pi t/T}$$

$$b_k = a_{-k}$$

$$x(t) \xleftrightarrow{\mathcal{FS}} a_k$$

$$x(-t) \xleftrightarrow{\mathcal{FS}} a_{-k}$$

$$x(-t) \xleftrightarrow{\mathcal{FS}} a_k \quad \text{if } x(t) \text{ is even.}$$

$$x(-t) \xleftrightarrow{\mathcal{FS}} -a_k \quad \text{if } x(t) \text{ is odd.}$$

$$\Leftrightarrow a_{-k} = a_k \quad (\text{even})$$

$$\Leftrightarrow a_{-k} = -a_k \quad (\text{odd})$$

3.5.4 Time scaling

$$x(\alpha t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(\alpha\omega_0)t} \quad (\text{periodic with period } T/\alpha)$$

3.5.5 Multiplications

$$x(t) \xleftrightarrow{\mathcal{F}\mathcal{S}} a_k$$

$$y(t) \xleftrightarrow{\mathcal{F}\mathcal{S}} b_k$$

$$x(t)y(t) \xleftrightarrow{\mathcal{F}\mathcal{S}} h_k = \sum_{l=-\infty}^{\infty} a_l b_{k-l} \quad \text{convolution} \quad (\text{Prob. 3.46})$$



3.5.6 Conjugation and conjugate symmetry (Prob. 3.42)

$$\begin{array}{c} x(t) \xleftrightarrow{\mathcal{F}S} a_k \\ x^*(t) \xleftrightarrow{\mathcal{F}S} a_{-k}^* \end{array}$$

If $x(t)$ is real, i.e., $x(t) = x^*(t)$,

$$a_{-k} = a_k^* \quad (\text{conjugate symmetric})$$

If $x(t)$ is real and even, then $a_k^* = a_{-k}$ and $a_k = a_{-k}$ $\therefore a_k = a_k^*$

If $x(t)$ is real and odd, then $a_k^* = a_{-k}$ and $a_k = -a_{-k}$ $\therefore a_k = -a_k^*$

3.5.7 Parseval's relation for continuous-time periodic signal

$$\frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=-\infty}^{\infty} |a_k|^2 \quad (\text{Prob. 3.46})$$

$$\frac{1}{T} \int_T |a_k e^{jk\omega_0 t}|^2 dt = \frac{1}{T} \int_T |a_k|^2 dt = |a_k|^2 : \text{average power in the } k\text{th harmonic component of } x(t)$$



Periodic Convolution

$$\int_T x(\tau) y(t - \tau) d\tau \xleftrightarrow{\mathcal{F}S} T a_k b_k$$

Differentiation

$$\frac{dx(t)}{dt} \xleftrightarrow{\mathcal{F}S} jk\omega_0 a_k = jk \frac{2\pi}{T} a_k$$

Integration

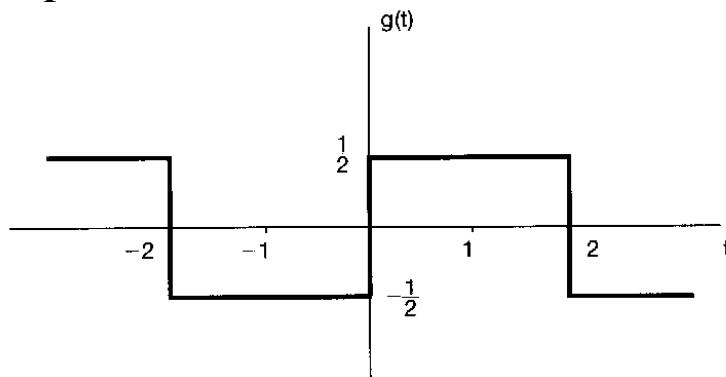
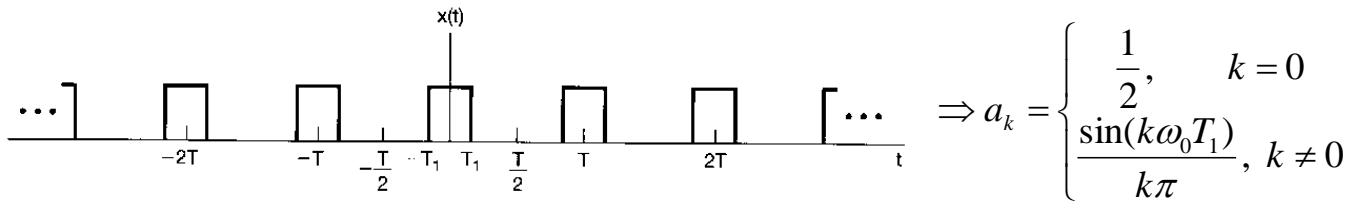
$$\int_{-\infty}^t x(\tau) d\tau \text{ (finite valued and periodic only if } a_0 = 0)$$

$$\xleftrightarrow{\mathcal{F}S} \left(\frac{1}{jk\omega_0} \right) a_k = \left(\frac{1}{jk(2\pi/T)} \right) a_k$$



Ex. 3.6) $x(t)$:

$$\omega_0 = \frac{2\pi}{T}, T = 4, T_1 = 1$$



$$d_k = \frac{1}{4} \int_{-2}^0 \left(-\frac{1}{2} \right) e^{-jk\omega_0 t} dt + \frac{1}{4} \int_0^2 \frac{1}{2} e^{-jk\omega_0 t} dt$$

$$\omega_0 = \frac{2\pi}{4} = \frac{\pi}{2}$$

$$g(t) = x(t-1) - 1/2$$

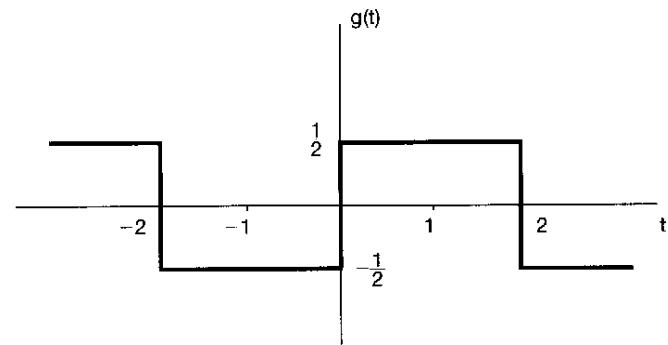
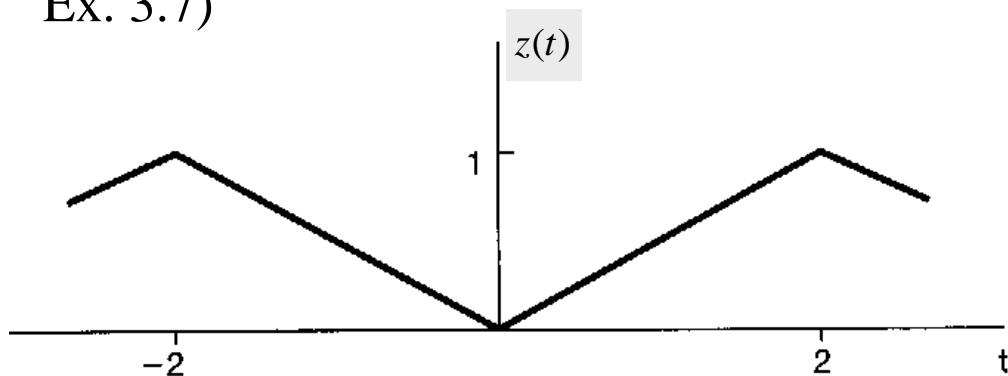
$$b_k = a_k e^{-jk\omega_0 t_0} = a_k e^{-jk\pi/2}$$

$$c_k = \begin{cases} 0, & \text{for } k \neq 0 \\ -\frac{1}{2}, & \text{for } k = 0 \end{cases}$$

$$d_k = \begin{cases} a_k e^{-jk\pi/2}, & \text{for } k \neq 0 \\ a_0 - \frac{1}{2}, & \text{for } k = 0 \end{cases}$$

$$d_k = \begin{cases} \frac{\sin(k\pi/2)}{k\pi} e^{-jk\pi/2} & \text{for } k \neq 0 \\ 0 & \text{for } k = 0 \end{cases}$$

Ex. 3.7)



$$z(t) = \sum_{k=-\infty}^{\infty} e_k e^{jk\omega_0 t}$$

$$e_k = \frac{1}{4} \left[\int_{-2}^0 -\frac{t}{2} e^{-jk\omega_0 t} dt + \int_0^2 \frac{t}{2} e^{-jk\omega_0 t} dt \right]$$

$$g(t) = \sum_{k=-\infty}^{\infty} d_k e^{jk\omega_0 t}$$

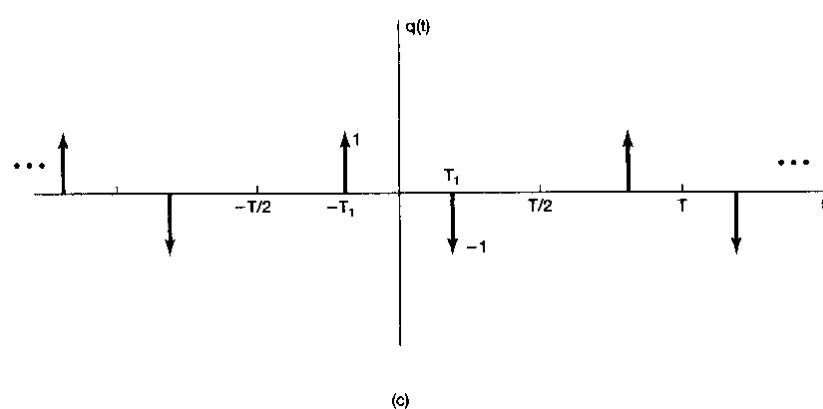
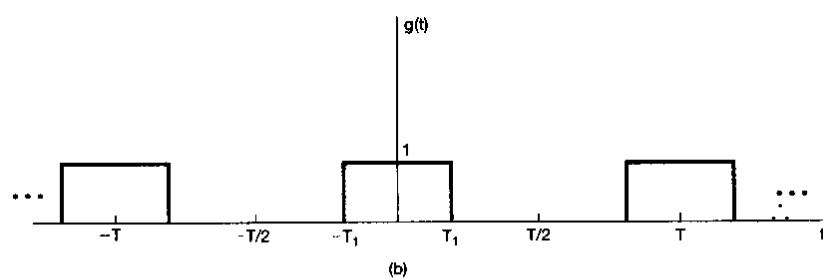
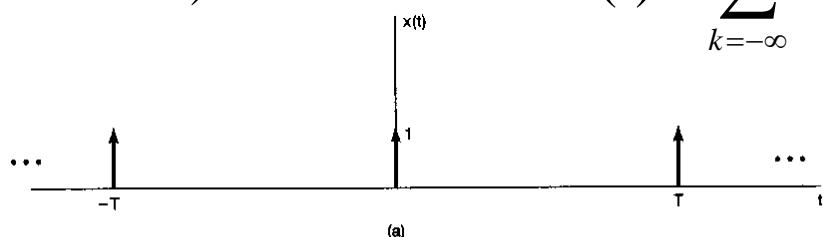
Differentiation of the current signal results in the signal of the Former example

$$g(t) = \frac{dz(t)}{dt} \Leftrightarrow d_k = jk\omega_0 e_k = jk(\pi/2)e_k$$

$$e_k = \frac{2d_k}{jk\pi} = \frac{2 \sin(k\pi/2)}{j(k\pi)^2} e^{-jk\pi/2}, \quad k \neq 0 \quad \text{and} \quad e_0 = \frac{1}{2}$$

Ex. 3.8)

$$x(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT)$$



$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} \delta(t)e^{-jk2\pi t/T} dt = \frac{1}{T}$$

$$x(t) = \sum_{k=-\infty}^{\infty} \frac{1}{T} e^{jk\omega_0 t}$$

$$q(t) = x(t + T_1) - x(t - T_1)$$

$$= \sum_{k=-\infty}^{\infty} b_k e^{jk\omega_0 t}$$

$$g(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}$$

$$b_k = e^{jk\omega_0 T_1} a_k - e^{-jk\omega_0 T_1} a_k$$

$$b_k = jk\omega_0 c_k$$

$$\therefore c_k = \frac{b_k}{jk\omega_0}$$

3.6 Fourier series representation of discrete-time periodic signals

3.6.1 Linear combinations of harmonically related complex exponentials

Discrete-time Periodic Signal

$$x[n] = x[n + N]$$

For the continuous-time periodic signals

$$x(t) = x(t + T)$$

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{+\infty} a_k e^{jk(2\pi/T)t}$$

As for the discrete-time signals

$$x[n] = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 n} = \sum_{k=-\infty}^{+\infty} a_k e^{jk(2\pi/N)n}$$



Harmonically related signals

$$\phi_k[n] = e^{jk\omega_0 n} = e^{jk(2\pi/N)n}, \quad k = 0, \pm 1, \pm 2, \dots$$

$$\phi_k[n] = \phi_{k+rN}[n] \quad (\because \phi_{k+rN}[n] = e^{j(k+rN)\omega_0 n} = e^{jk\omega_0 n} e^{jrN\omega_0 n} = e^{jk\omega_0 n} e^{jrN(2\pi/N)n} = e^{jk\omega_0 n})$$

$$\phi_N[n] = \phi_0[n]$$

$$\phi_{N+1}[n] = \phi_1[n]$$

$$x[n] = \sum_k a_k \phi_k[n] = \sum_k a_k e^{jk\omega_0 n} = \sum_k a_k e^{jk2\pi n/N}$$

↓

It is sufficient to include
 N harmonic components.

$$x[n] = \sum_{k=<N>} a_k \phi_k[n] = \sum_{k=<N>} a_k e^{jk\omega_0 n} = \sum_{k=<N>} a_k e^{jk2\pi n/N}$$

3.6.2 Determination of the Fourier series representation of a periodic signal

$$x[0] = \sum_{k=<N>} a_k e^{jk(2\pi/N) \cdot 0}$$

$$\begin{aligned} x[1] &= \sum_{k=<N>} a_k e^{jk(2\pi/N) \cdot 1} \\ &\vdots \end{aligned}$$

$$x[N-1] = \sum_{k=<N>} a_k e^{jk(2\pi/N) \cdot (N-1)}$$

$k = < N >$
$k = 0, 1, \dots, N-1$
$k = 1, 2, \dots, N$
$k = 2, 3, \dots, N+1$

$$x[n] = \sum_{k=0}^{N-1} a_k e^{jk(2\pi/N)n}$$

Multiplying both sides by $e^{-jr(2\pi/N)n}$ and summing over a period

$$\sum_{n=<N>} x[n] e^{-jr(2\pi/N)n} = \sum_{n=<N>} \sum_{k=<N>} a_k e^{jk(2\pi/N)n} e^{-jr(2\pi/N)n} = \sum_{n=<N>} \sum_{k=<N>} a_k e^{j(k-r)(2\pi/N)n}$$

$$= \sum_{k=<N>} a_k \underbrace{\sum_{n=<N>} e^{j(k-r)(2\pi/N)n}}_?$$

$$\sum_{n=<N>} e^{j(k-r)(2\pi/N)n} = \begin{cases} N, & k-r = 0, \pm N, \pm 2N, \dots \\ 0, & otherwise \end{cases}$$



Problem 3.54 Show that

$$\sum_{n=-N}^{N-1} e^{j(k-r)(2\pi/N)n} = \begin{cases} N, & k-r = 0, \pm N, \pm 2N, \dots \\ 0, & \text{otherwise} \end{cases}$$

i) $k-r \neq mN$ for $m=0, \pm 1, \pm 2$, etc.

$$\sum_{n=0}^{N-1} \exp[j(k-r)\frac{2\pi}{N}n] = \frac{1 - \exp[j(k-r)\frac{2\pi}{N}N]}{1 - \exp[j(k-r)\frac{2\pi}{N}]} = 0$$

ii) $k-r = mN$

$$\begin{aligned} \sum_{n=0}^{N-1} \exp[j(k-r)\frac{2\pi}{N}n] &= \sum_{n=0}^{N-1} \exp[jmN \cdot \frac{2\pi}{N} \cdot n] \\ &= \sum_{n=0}^{N-1} \exp[j2\pi \cdot mn] = N \end{aligned}$$

$$\therefore \sum_{n=0}^{N-1} \exp[j(k-r)\frac{2\pi}{N}n] = N\delta(k-r-mN)$$



Discrete Fourier series pair

$$x[n] = \sum_{k=-N}^{N-1} a_k e^{jk\omega_0 n} = \sum_{k=-N}^{N-1} a_k e^{jk(2\pi/N)n}$$

synthesis equation

$$a_k = \frac{1}{N} \sum_{n=-N}^{N-1} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{n=-N}^{N-1} x[n] e^{-jk(2\pi/N)n}$$

analysis equation

$\{a_k\}$ Fourier series coefficients of $x[n]$

or

Spectral coefficients of $x[n]$

$$x[n] = a_0 \phi_0[n] + a_1 \phi_1[n] + \dots + a_{N-1} \phi_{N-1}[n]$$

$$x[n] = a_1 \phi_1[n] + a_2 \phi_2[n] + \dots + a_N \phi_N[n]$$

$a_k = a_{k+N} \rightarrow a_k$ is also a periodic sequence



Ex. 3.12)



$$a_k = \frac{1}{N} \sum_{n=-N_1}^{+N_1} e^{-jk(2\pi/N)n}$$

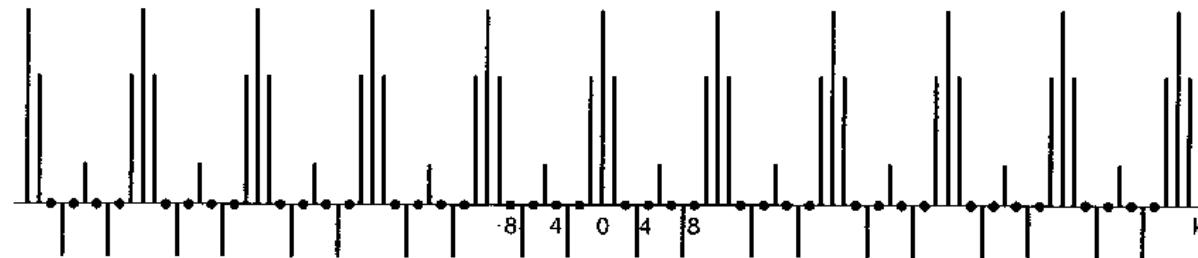
$$a_k = \frac{1}{N} \sum_{m=0}^{2N_1} e^{-jk(2\pi/N)(m-N_1)}$$

$$= \frac{1}{N} e^{-jk(2\pi/N)N_1} \sum_{m=0}^{2N_1} e^{-jk(2\pi/N)m}$$

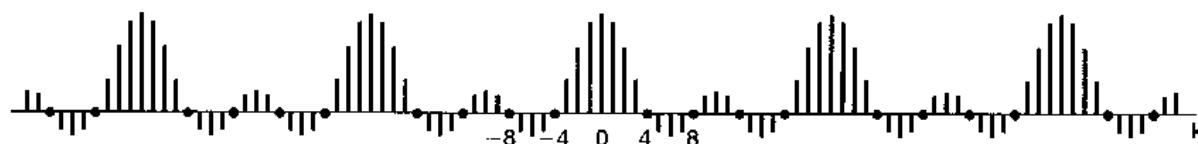
$$\begin{aligned} a_k &= \frac{1}{N} e^{jk(2\pi/N)N_1} \left(\frac{1 - e^{-jk2\pi(2N_1+1)/N}}{1 - e^{-jk2\pi/N}} \right) \\ &= \frac{1}{N} \frac{e^{-jk(2\pi/2N)}}{e^{-jk(2\pi/2N)}} \left(\frac{e^{jk2\pi(N_1+1/2)/N} - e^{-jk2\pi(N_1+1/2)/N}}{e^{jk(2\pi/2N)} - e^{-jk(2\pi/2N)}} \right) \\ &= \frac{1}{N} \frac{\sin[2\pi k(N_1 + 1/2)/N]}{\sin(\pi k/N)} \quad k \neq 0, \pm N, \pm 2N, \dots \end{aligned}$$

$$a_k = \frac{2N_1 + 1}{N}, \quad k = 0, \pm N, \pm 2N, \dots$$

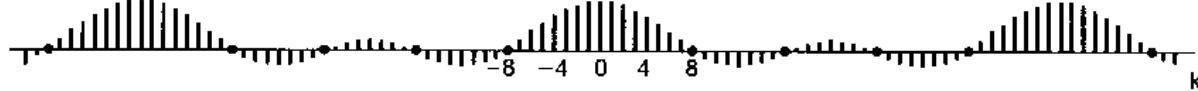
Plots of Na_k



(a) $N = 10$

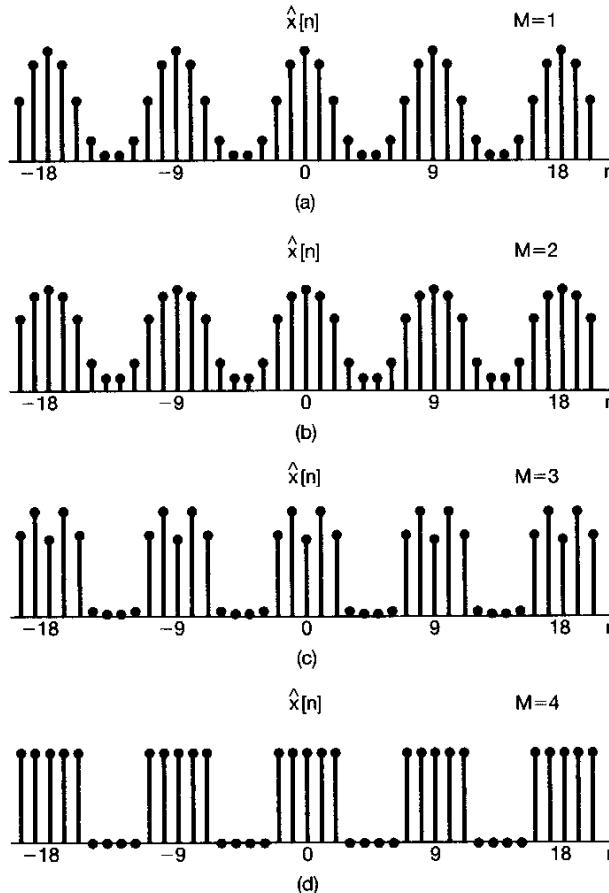


(b) $N = 20$



(c) $N = 40$

Partial sums for the periodic square wave



$$\hat{x}[n] = \sum_{k=-M}^{+M} a_k e^{jk(2\pi/N)n} \quad N : \text{odd}$$

$$\hat{x}[n] = \sum_{k=-M+1}^{+M} a_k e^{jk(2\pi/N)n} \quad N : \text{even}$$

$$x[n] \xrightarrow{\mathcal{FS}} a_k : \text{equivalent set}$$

Recover

Any discrete-time **periodic** seq. $x[n]$ is completely specified by a finite number N of parameters

3.7 Properties of discrete-time Fourier series

$$x[n] \xleftrightarrow{\mathcal{FS}} a_k$$

3.7.1 Multiplication

$$x[n]y[n] \xleftrightarrow{\mathcal{FS}} d_k = \sum_{l=-N}^{N-1} a_l b_{k-l} \quad : \text{periodic convolution}$$

3.7.2 First difference

$$a_k = \frac{1}{N} \sum_{n=-N}^{N-1} x[n] e^{-jk(2\pi/N)n}$$

$$\begin{aligned} b_k &= \frac{1}{N} \sum_{n=-N}^{N-1} x[n-1] e^{-jk(2\pi/N)n} = \frac{1}{N} e^{-jk(2\pi/N)} \sum_{n=-N}^{N-1} x[n-1] e^{-jk(2\pi/N)(n-1)} \\ &= e^{-jk(2\pi/N)} a_k \end{aligned}$$

$$x[n] - x[n-1] \xleftrightarrow{\mathcal{FS}} a_k (1 - e^{-jk(2\pi/N)})$$



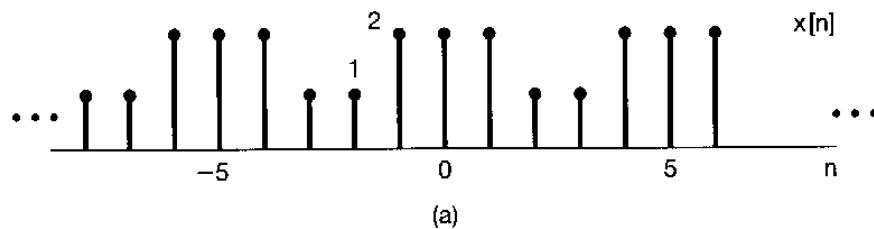
3.7.3 Parseval's relation to discrete-time periodic signals

$$\frac{1}{N} \sum_{n=<N>} |x[n]|^2 = \sum_{k=<N>} |a_k|^2$$

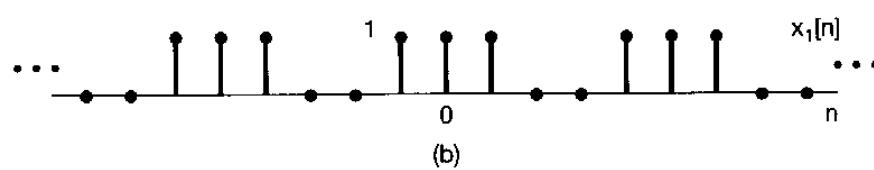


3.7.4 Examples

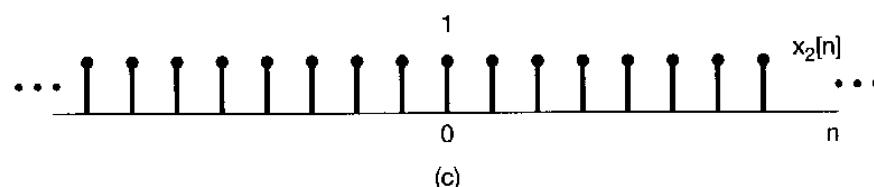
Ex. 3.14)



(a)



(b)



(c)

$$x[n] = x_1[n] + x_2[n]$$

$$a_k = b_k + c_k$$

$$b_k = \begin{cases} \frac{\sin(3k\pi/5)}{5\sin(k\pi/5)} & \text{for } k \neq 0, \pm 5, \pm 10, \dots \\ \frac{3}{5} & \text{for } k = 0, \pm 5, \pm 10, \dots \end{cases}$$

$$c_0 = \frac{1}{5} \sum_{n=0}^4 x_2[n] = 1$$

Example 3.14

1. $x[n]$ is periodic with period $N = 6$.

$$2. \sum_{n=0}^5 x[n] = 2. \quad \Rightarrow \quad a_0 = \frac{1}{3}$$

$$3. \sum_{n=2}^7 (-1)^n x[n] = 1.$$

$$(-1)^n = e^{-j\pi n} = e^{-j(2\pi/6)3n} \quad \Rightarrow \quad a_3 = \frac{1}{6}$$

4. $x[n]$ has the minimum power per period. $\Rightarrow a_1 = a_2 = a_4 = a_5 = 0$

$$\begin{aligned}\therefore x[n] &= a_0 + a_3 e^{j\pi n} \\ &= \frac{1}{3} + \frac{1}{6} (-1)^n\end{aligned}$$



3.8 Fourier series and LTI systems

$$H(s) = \int_{-\infty}^{\infty} h(\tau) e^{-s\tau} d\tau \quad H(s), H(z) : \text{system functions}$$

$$H(z) = \sum_{k=-\infty}^{\infty} h[k] z^{-k}$$

$$H(j\omega) = \int_{-\infty}^{\infty} h(t) e^{-j\omega t} dt \quad H(j\omega) : \text{frequency response}$$

$e^{j\omega n}$: input $h[n]$: impulse response of the LTI system

$$\begin{aligned} y[n] &= \sum_{k=-\infty}^{\infty} h[k] x[n-k] = \sum_{k=-\infty}^{\infty} h[k] e^{j\omega(n-k)} \\ &= e^{j\omega n} H(e^{j\omega}) \end{aligned}$$

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k] e^{-j\omega k} \quad : \text{frequency response}$$



$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \quad \Rightarrow \quad y(t) = \sum_{k=-\infty}^{\infty} a_k H(jk\omega_0) e^{jk\omega_0 t}$$

Ex. 3.16)

$$x(t) = \sum_{k=-3}^{+3} a_k e^{jk2\pi t} \quad (a_0 = 1, a_1 = a_{-1} = \frac{1}{4}, a_2 = a_{-2} = \frac{1}{2}, a_3 = a_{-3} = \frac{1}{3})$$

$$h(t) = e^{-t} u(t)$$

$$H(j\omega) = \int_0^\infty e^{-\tau} e^{-j\omega\tau} d\tau = -\frac{1}{1+j\omega} e^{-\tau} e^{-j\omega\tau} \Big|_0^\infty = \frac{1}{1+j\omega}$$



$$y(t) = \sum_{k=-3}^3 b_k e^{jk2\pi t}, \quad \text{with } b_k = a_k H(jk2\pi)$$

$$b_0 = 1$$

$$b_1 = \frac{1}{4} \left(\frac{1}{1+j2\pi} \right), \quad b_{-1} = \frac{1}{4} \left(\frac{1}{1-j2\pi} \right)$$

$$b_2 = \frac{1}{2} \left(\frac{1}{1+j4\pi} \right), \quad b_{-2} = \frac{1}{2} \left(\frac{1}{1-j4\pi} \right)$$

$$b_3 = \frac{1}{3} \left(\frac{1}{1+j6\pi} \right), \quad b_{-3} = \frac{1}{3} \left(\frac{1}{1-j6\pi} \right)$$

Since $b_k^* = b_{-k}$, $y(t) = b_0 + 2 \sum_{k=1}^3 \operatorname{Re}\{b_k e^{j2\pi kt}\}$

$$y(t) = 1 + 2 \sum_{k=1}^3 D_k \cos(2\pi k t + \theta_k) \quad \text{or} \quad y(t) = 1 + 2 \sum_{k=1}^3 [E_k \cos 2\pi k t - F_k \sin 2\pi k t],$$

where $b_k = D_k e^{j\theta_k} = E_k + jF_k$

ex) $D_1 = |b_1| = \frac{1}{4\sqrt{1+4\pi^2}}$, $\theta_1 = \angle b_1 = -\tan^{-1}(2\pi)$

$$E_1 = \operatorname{Re}\{b_1\} = \frac{1}{4(1+4\pi^2)}, \quad F_1 = \operatorname{Im}\{b_1\} = -\frac{\pi}{2(1+4\pi^2)}$$



Ex. 3.17) Discrete-time system

$$y[n] = \sum_{k=-N}^{N-1} a_k H(e^{j(2\pi k/N)}) e^{jk(2\pi/N)n}$$

$$h[n] = \alpha^n u[n]$$

$$x[n] = \cos\left(\frac{2\pi n}{N}\right) = \frac{1}{2} e^{j(2\pi/N)n} + \frac{1}{2} e^{-j(2\pi/N)n}$$

$$H(e^{j\omega}) = \sum_{n=0}^{\infty} \alpha^n e^{-j\omega n} = \sum_{n=0}^{\infty} (\alpha e^{-j\omega})^n$$

$$H(e^{j\omega}) = \frac{1}{1 - \alpha e^{-j\omega}}$$



$$\begin{aligned}
y[n] &= \frac{1}{2} H(e^{j2\pi/N}) e^{j(2\pi/N)n} + \frac{1}{2} H(e^{-j2\pi/N}) e^{-j(2\pi/N)n} \\
&= \frac{1}{2} \left(\frac{1}{1 - \alpha e^{-j2\pi/N}} \right) e^{j(2\pi/N)n} + \frac{1}{2} \left(\frac{1}{1 - \alpha e^{j2\pi/N}} \right) e^{-j(2\pi/N)n}
\end{aligned}$$

If we let $\frac{1}{1 - \alpha e^{-j2\pi/N}} = r e^{j\theta}$

$$y[n] = r \cdot \cos\left(\frac{2\pi}{N}n + \theta\right)$$

The output of the sinusoidal input for LTI systems

$$x[n] = e^{j\frac{2\pi}{N}kn} = \boxed{\cos\left(\frac{2\pi}{N}kn\right)} + j\boxed{\sin\left(\frac{2\pi}{N}kn\right)}$$

→ $y[n] = H(e^{j\frac{2\pi}{N}k}) \cdot e^{j\frac{2\pi}{N}kn}$

$$H(e^{j\frac{2\pi}{N}k}) = \sum_{n=-\infty}^{\infty} h[n] \cdot \exp\left[-j\frac{2\pi}{N}kn\right]$$

$$\therefore y[n] = \left|H(e^{j\frac{2\pi}{N}k})\right| \exp\left[j\angle H(e^{j\frac{2\pi}{N}k})\right] \cdot \exp\left[j\frac{2\pi}{N}kn\right]$$

$$= \left|H(e^{j\frac{2\pi}{N}k})\right| \exp\left[j\left(\frac{2\pi}{N}kn + \angle H(e^{j\frac{2\pi}{N}k})\right)\right]$$

$$= \boxed{\left|H(e^{j\frac{2\pi}{N}k})\right| \cos\left[\frac{2\pi}{N}kn + \angle H(e^{j\frac{2\pi}{N}k})\right]}$$

$$+ j \boxed{\left|H(e^{j\frac{2\pi}{N}k})\right| \sin\left[\frac{2\pi}{N}kn + \angle H(e^{j\frac{2\pi}{N}k})\right]}$$



The output of the LTI systems using Fourier series

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \quad \Rightarrow \quad y(t) = \sum_{k=-\infty}^{\infty} a_k H(jk\omega_0) e^{jk\omega_0 t} \quad \left(\omega_0 = \frac{2\pi}{T} \right)$$

$$x[n] = \sum_{k=<N>} a_k e^{jk\omega_0 n} \quad \Rightarrow \quad y[n] = \sum_{k=<N>} a_k H(e^{jk\omega_0}) e^{jk\omega_0 n} \quad \left(\omega_0 = \frac{2\pi}{N} \right)$$

$$x(t) = A \cos(\omega_0 t + \theta_0) \Rightarrow y(t) = A |H(j\omega_0)| \cos[\omega_0 t + \theta_0 + \angle H(j\omega_0)]$$

$$x(t) = A \sin(\omega_0 t + \theta_0) \Rightarrow y(t) = A |H(j\omega_0)| \sin[\omega_0 t + \theta_0 + \angle H(j\omega_0)]$$

$$x[n] = A \cos(\omega_0 n + \theta_0) \Rightarrow y[n] = A |H(e^{j\omega_0})| \cos[\omega_0 n + \theta_0 + \angle H(e^{j\omega_0})]$$

$$x[n] = A \sin(\omega_0 n + \theta_0) \Rightarrow y[n] = A |H(e^{j\omega_0})| \sin[\omega_0 n + \theta_0 + \angle H(e^{j\omega_0})]$$

where $H(e^{j\omega}) = \sum_{n=-\infty}^{\infty} h[n]e^{-j\omega n}$, $H(j\omega) = \int_{-\infty}^{\infty} h(t)e^{-j\omega t} dt$



3.9 Filtering

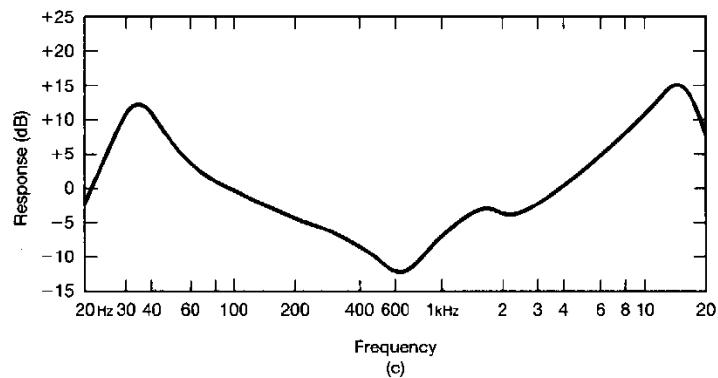
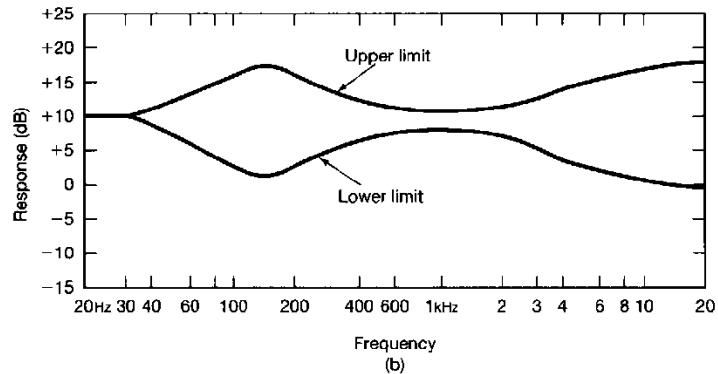
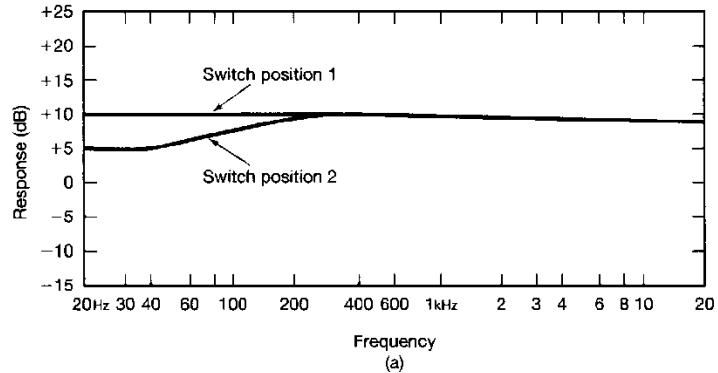
$$y(t) = \sum_{k=-\infty}^{\infty} a_k H(jk\omega_0) e^{jk\omega_0 t}$$

Filter

3.9.1 Frequency shaping filter

Change the shape of the spectrum

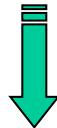
Ex: Equalizer
Bass control
Treble control



Differentiator

$$y(t) = \frac{dx(t)}{dt}$$

$$H(j\omega) = j\omega$$

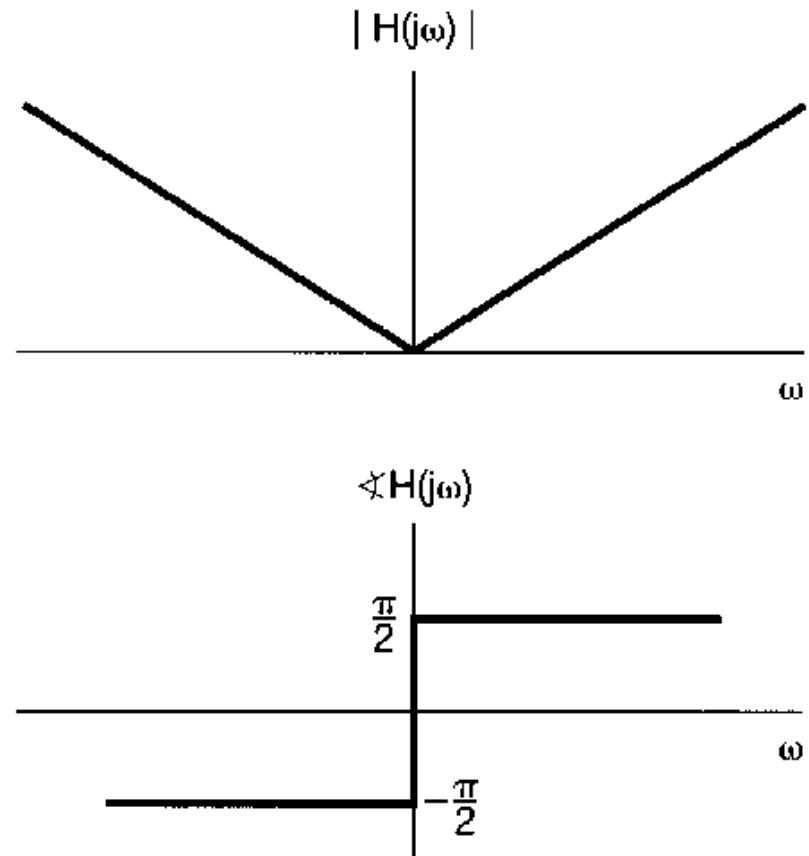


- highpass filter

Ex.) Figure 3.24, page 235

$$\cos \omega t \rightarrow -\omega \sin \omega t = \omega \cos(\omega t + \frac{\pi}{2})$$

$$\sin \omega t \rightarrow \omega \cos \omega t = \omega \sin(\omega t + \frac{\pi}{2})$$



For Discrete-time systems

$$y[n] = x[n] - x[n-1]$$

$$x[n] = \sin \omega n$$

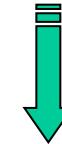
$$y[n] = \sin \omega n - \sin \omega(n-1)$$

$$= 2 \cos(\omega n - \frac{\omega}{2}) \sin(\frac{\omega}{2})$$

$$H(e^{j\omega}) = 1 - e^{-j\omega}$$

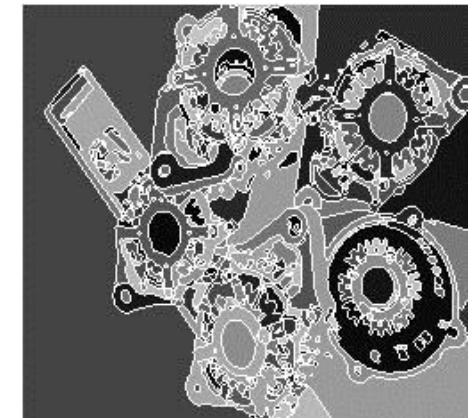
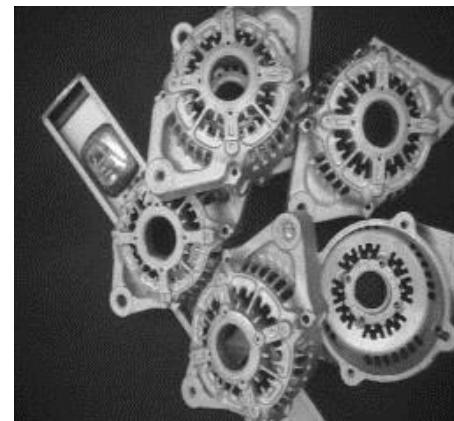
$$= e^{-j\omega/2} (e^{j\omega/2} - e^{-j\omega/2})$$

$$= 2j \sin(\omega/2) e^{-j\omega/2}$$



Highpass filter

Edge detection



For Discrete-time systems

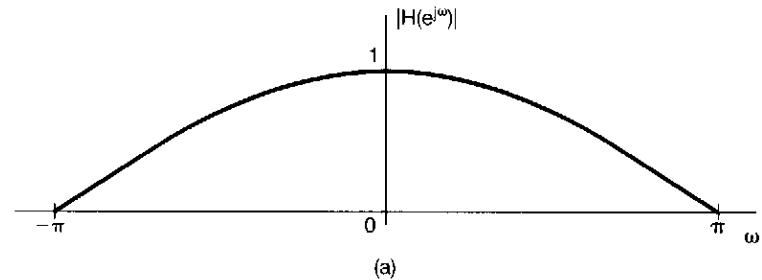
$$y[n] = \frac{1}{2}(x[n] + x[n-1])$$

In frequency domain

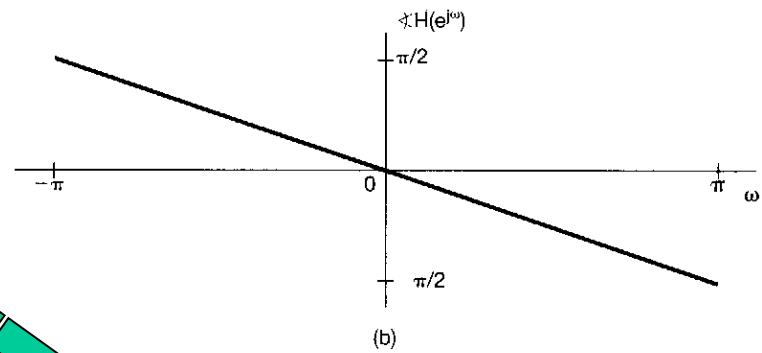
$$H(e^{j\omega}) = \frac{1}{2}[1 + e^{-j\omega}] = e^{-j\omega/2} \cos(\omega/2)$$

In time domain, $x[n] = \sin \omega n$

$$\begin{aligned} y[n] &= \frac{1}{2}(\sin \omega n + \sin \omega(n-1)) \\ &= \sin(\omega n - \omega/2) \cos(\omega/2) \end{aligned}$$



(a)

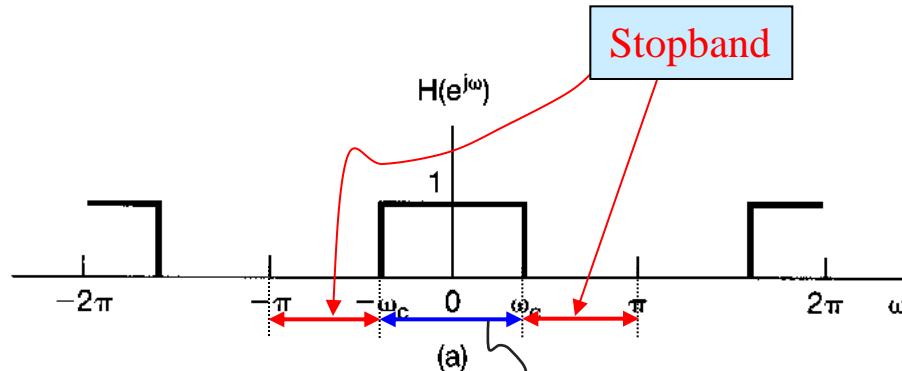


(b)

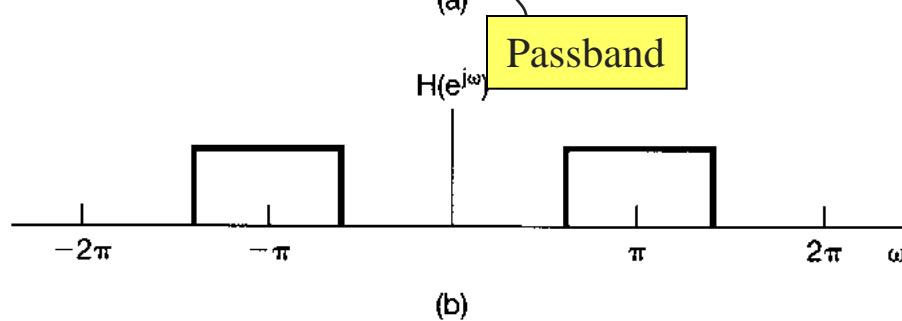


Lowpass filter

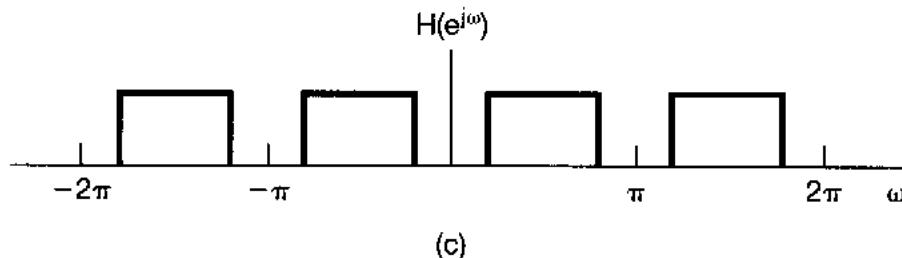
3.9.2 Frequency selective filters



Lowpass filter

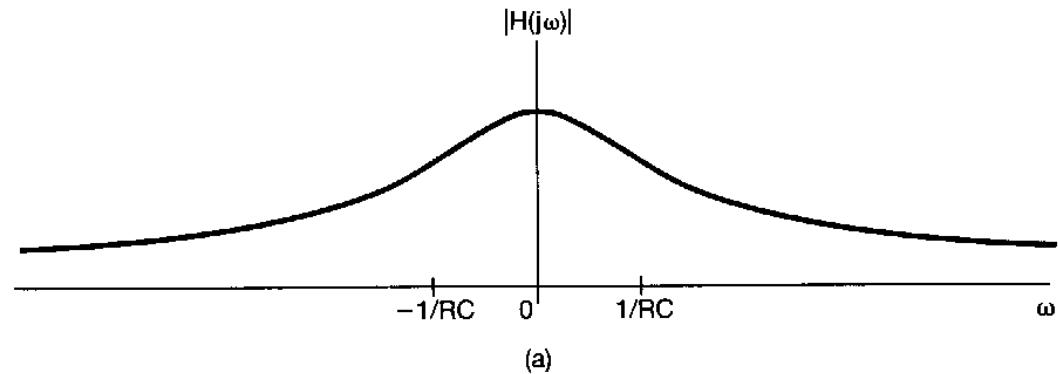
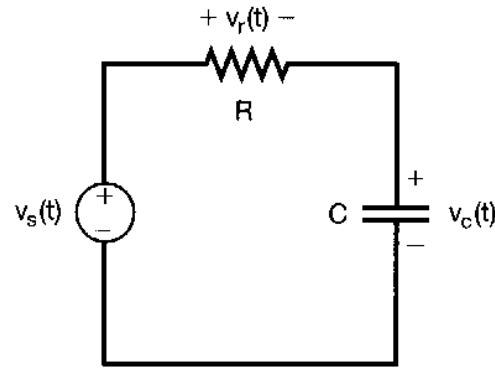


Highpass filter



Bandpass filter

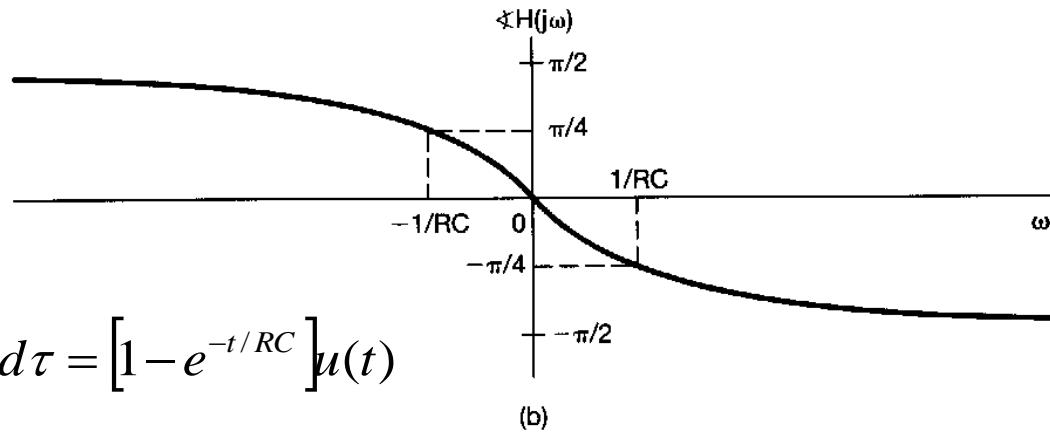
3.10 Examples of continuous-time filters described by differential equations



$$H(j\omega) = \frac{1}{1 + RCj\omega}$$

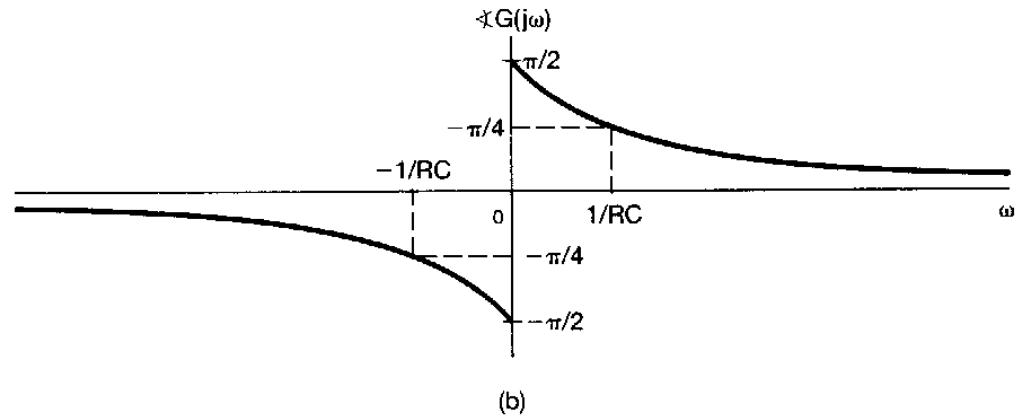
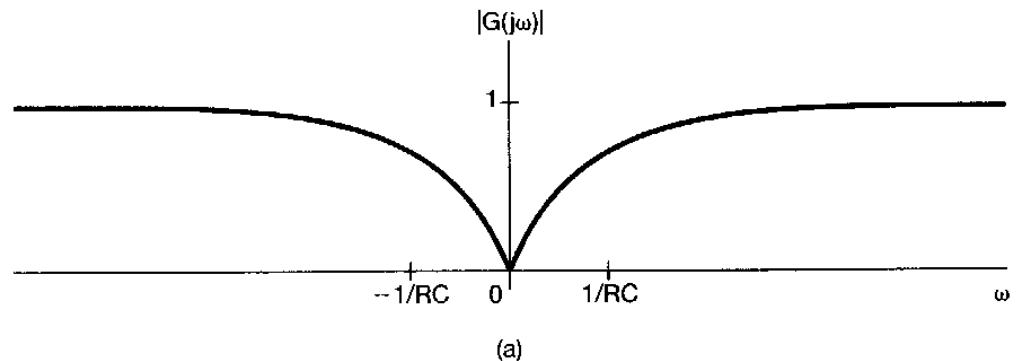
$$h(t) = \frac{1}{RC} e^{-t/RC} u(t)$$

$$s(t) = u(t) * h(t) = \int_{-\infty}^t h(\tau) d\tau = [1 - e^{-t/RC}] u(t)$$



For the voltage across the resistor R

$$G(j\omega) = \frac{j\omega RC}{1 + j\omega RC}$$



3.11 Examples of discrete-time filters described by difference equations

3.11.1 First-order recursive discrete-time filters

$$y[n] = ay[n-1] + x[n]$$

$$y[n] - ay[n-1] = x[n]$$

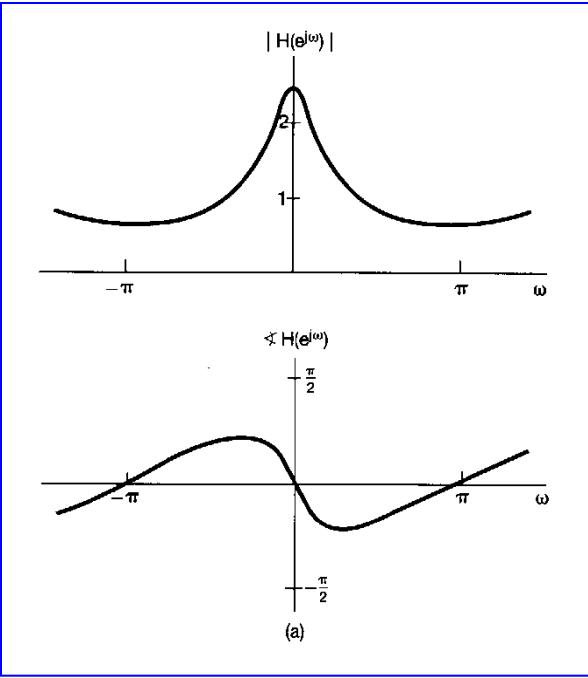
$$H(e^{jw})e^{jwn} - aH(e^{jw})e^{jw(n-1)} = e^{jwn}$$

$$(1 - ae^{-jw})H(e^{jw})e^{jwn} = e^{jwn}$$

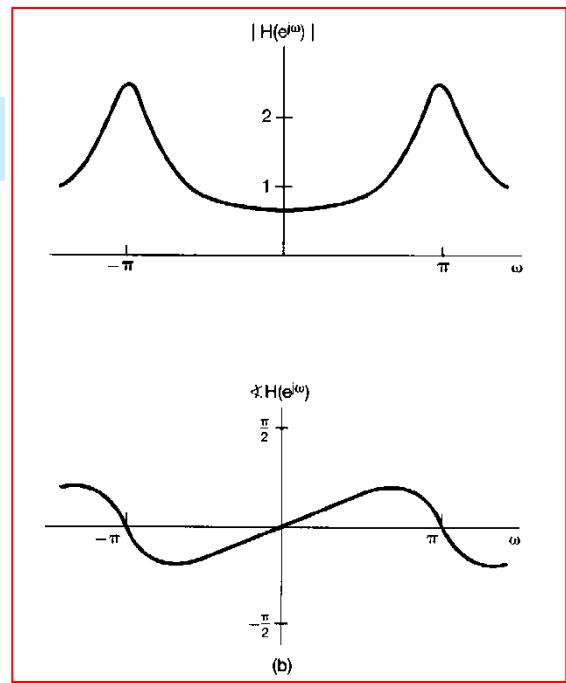
$$H(e^{jw}) = \frac{1}{(1 - ae^{-jw})}$$



$0 < a < 1$



$-1 < a < 0$



$$h[n] = a^n u[n]$$

$s[n] = u[n] * h[n]$: step response

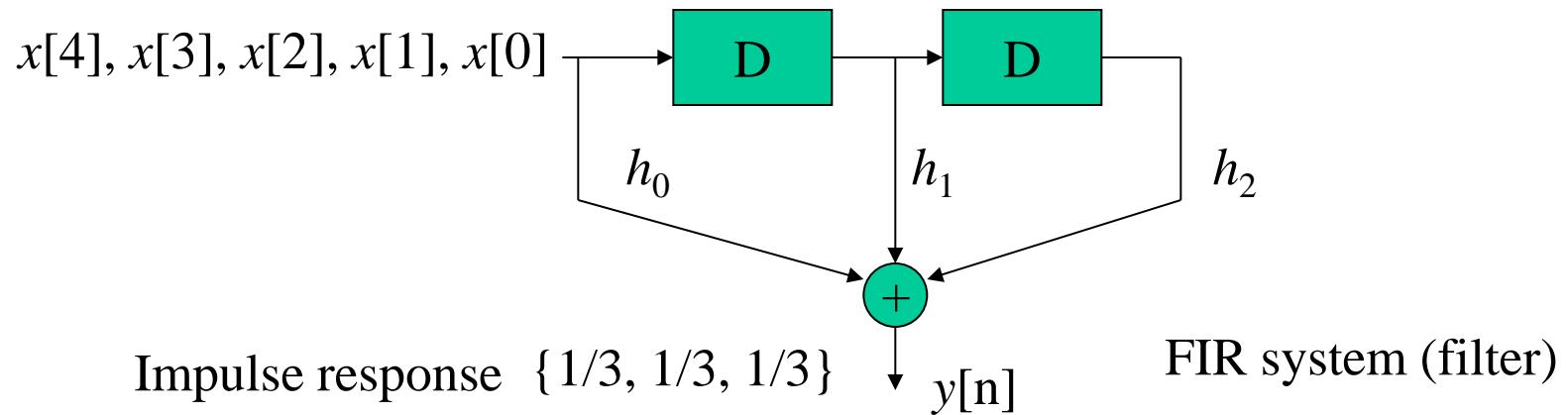
$$H(e^{j\omega}) = 1 + ae^{-j\omega} + a^2 e^{-j2\omega} + \dots$$

$$= \frac{1 - a^{n+1}}{1 - a} u[n]$$

$$= \frac{1}{1 - ae^{-j\omega}}$$

3.11.2 Nonrecursive discrete-time filters

$$y[n] = \sum_{k=-N}^M b_k x[n-k] \quad \text{Moving Average}$$

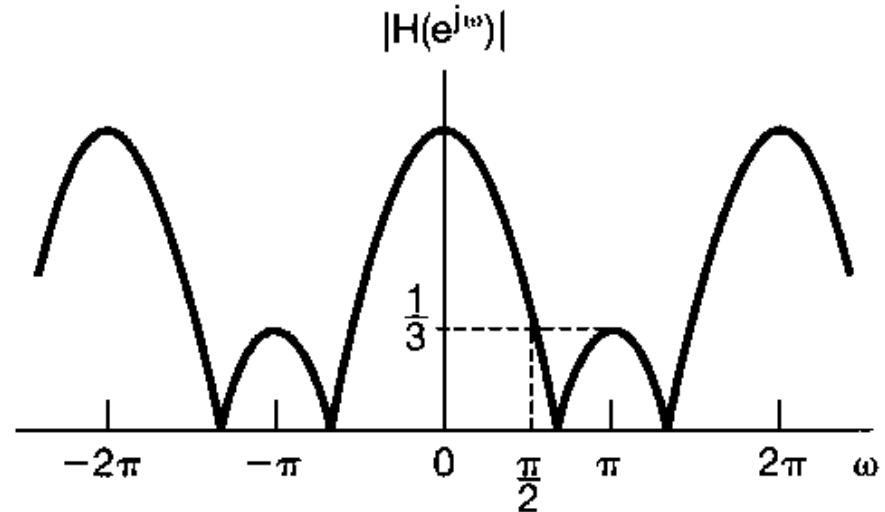


$$y[n] = \frac{1}{3}(x[n-1] + x[n] + x[n+1])$$

$$y[n] = \frac{1}{3}(x[n] + x[n-1] + x[n-2])$$

$$H(e^{j\omega}) = \frac{1}{3}[e^{j\omega} + 1 + e^{-j\omega}] = \frac{1}{3}(1 + 2\cos\omega)$$

$$\begin{aligned} H(e^{j\omega}) &= \frac{1}{3}[1 + e^{-j\omega} + e^{-j2\omega}] \\ &= \frac{1}{3}e^{-j\omega}(e^{j\omega} + 1 + e^{-j\omega}) \\ &= \frac{1}{3}e^{-j\omega}(1 + 2\cos\omega) \end{aligned}$$



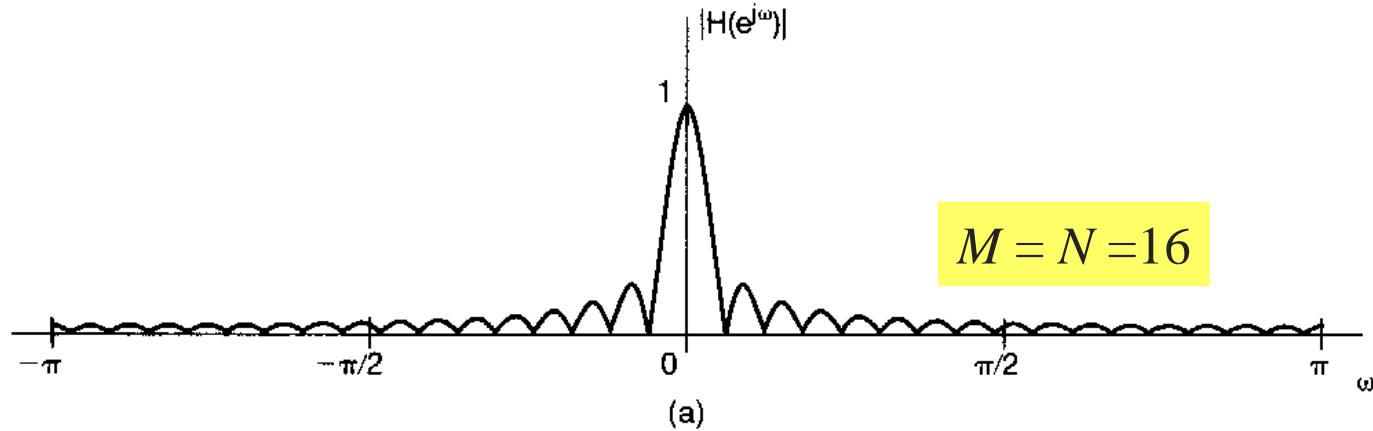
$$\{h_0, h_1, h_2\} = \{1/4, 1/2, 1/4\}$$

$$\begin{aligned} H(e^{j\omega}) &= \frac{1}{4} + \frac{1}{2}e^{-j\omega} + \frac{1}{4}e^{-j2\omega} = e^{-j\omega}\left(\frac{1}{4}e^{j\omega} + \frac{1}{2} + \frac{1}{4}e^{-j\omega}\right) \\ &= \frac{1}{2}e^{-j\omega}(1 + \cos\omega) \end{aligned}$$

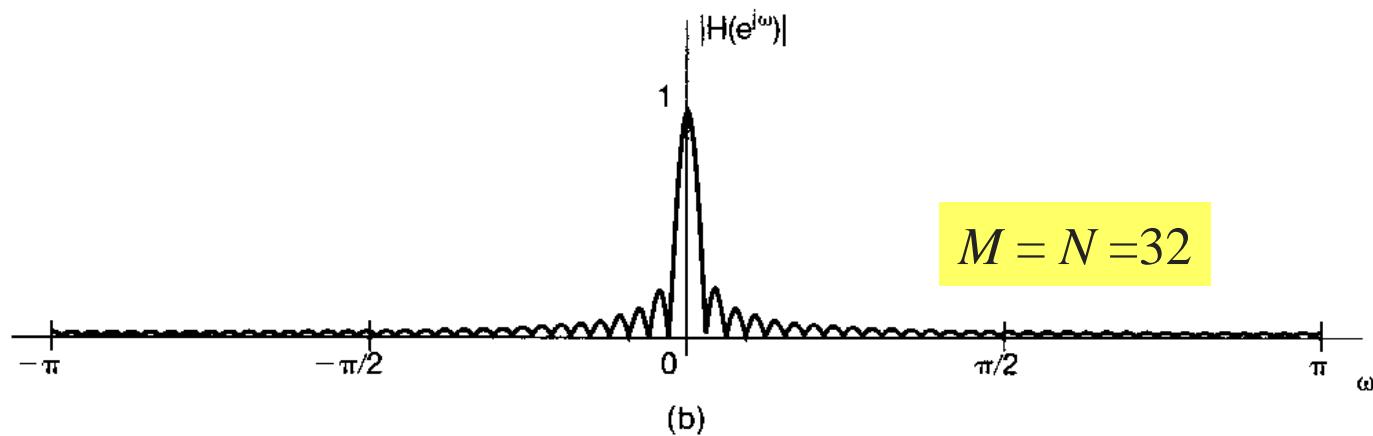
$$y[n] = \frac{1}{N+M+1} \sum_{k=-N}^M x[n-k]$$

$$H(e^{j\omega}) = \frac{1}{N+M+1} \sum_{k=-N}^M e^{-j\omega k}$$

$$H(e^{j\omega}) = \frac{1}{N+M+1} e^{-j\omega[(N-M)/2]} \frac{\sin[\omega(M+N+1)/2]}{\sin(\omega/2)}$$



(a)



(b)

$$y[n] = \frac{x[n] - x[n-1]}{2}$$

$$H(e^{j\omega}) = \frac{1}{2}[1 - e^{-j\omega}] = je^{j\omega/2} \sin(\omega/2)$$

