

2011년2학기  
임베디드시스템 응용 (#514118 )

#4. Timer\_2

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# 순서

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- ▶ Character LCD 사용법
- ▶ Clock/Buzzer output controller
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  - ▶ Control registers
  - ▶ Codes

# EVM에 장착된 character LCD

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## ▶ 문자 LCD

- ▶ 정해진 문자 (사용자 기호 입력 가능)를 표시하는 LCD
- ▶ 품명: AX07001 by Apex display It.
- ▶ 특징: 16x2 character LCD
  - ▶ 표시가능 문자 set: 기호, 숫자, 영어 알파벳 대소문자, 일어 가타가나 등

## ▶ MUC와의 연결

- ▶ LCD 제어를 위해 7개의 digital output 사용
- ▶ 4bit data transfer 방법 이용: 1byte data를 4bit씩 나누어 2번에 전송 → DB4~DB7 ↔ P0.0~P0.3
- ▶ Control bus : RS=P6.4, RW=P6.5, E=P6.6

# Code to use 16x2 char. LCD

```
#include "lcd2.h"
```

```
void main(void)
```

```
{
```

```
    //LCD init.
```

```
    wLCDinit(); //make input
```

```
    //전체 LCD를 클리어
```

```
    wLCDclr();
```

```
    //둘째 줄, 두번째 칸에 커서 표시
```

```
    wLCDcsron(1,1,1);
```

```
    wLCDcsron(1,1,0); //커서 지우기
```

```
    //문자 1개를 첫번째 4번째 칸에 A표시
```

```
    wLCDputc(0,3,'A');
```

```
    wLCDblink(0,3,1); //위 문자 blinking
```

```
    //(1,3) 위치부터 문자열 표시
```

```
    wLCDputs(1,3,"Hello");
```

```
}
```

'lcd2.c' 파일에 정의된 함수들의 prototype이 작성되어 있는 헤더 파일

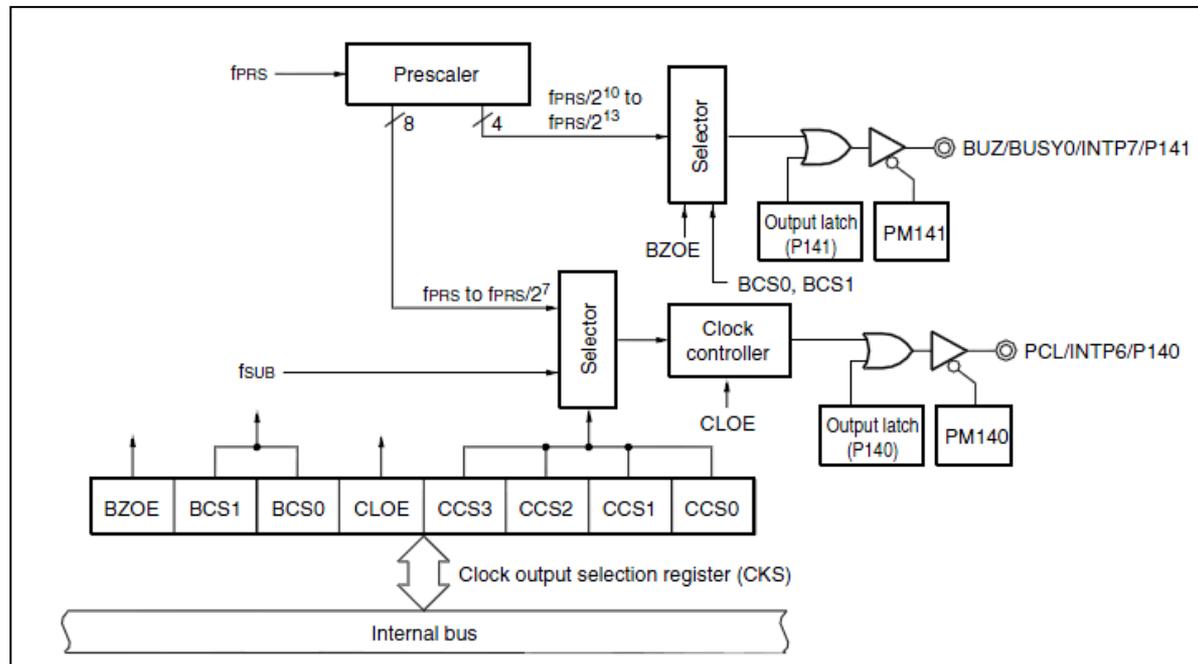
## LCD사용법

- lcd2.c source file을 프로젝트에 추가
- include header file
- 모두 6개의 함수 제공
- 모든 함수의 인자(argument)는 unsigned char 형으로 해야 함.
- 16x2 칸의 위치 지정은 0~15까지로 표시.

# Ch. 12: Clock/Buzzer output controller

## ▶ 기능

- ▶ 정해진 주파수의 클럭 신호를 생성하여 출력하는 장치
- ▶ BUZ/P141-버저용 클럭 출력용 핀
- ▶ PCL/INTP6/P140-클럭 신호 출력용 핀



# Control registers

## ▶ Clock output selection reg. (CKS)

▶ ON/OFF 제어: BZOE, CLOE (1 → on, 0 → off)

▶ BUZ 출력 클럭 주파수 결정 ; [BCS1:BCS0]

▶ 0 →  $f_{PRS}/2^{10}$

▶ 1 →  $f_{PRS}/2^{11}$

▶ 2 →  $f_{PRS}/2^{12}$

▶ 3 →  $f_{PRS}/2^{13}$

▶ PCL 출력 클럭 주파수 결정; [CCS3~CCS0]

▶  $f_{PRS}/2 \sim f_{PRS}/2^7$ ,  $f_{SUB}$

Figure 12-2. Format of Clock Output Selection Register (CKS)

Address: FF40H After reset: 00H R/W

Symbol	<7>	6	5	<4>	3	2	1	0
CKS	BZOE	BCS1	BCS0	CLOE	CCS3	CCS2	CCS1	CCS0

BZOE	BUZ output enable/disable specification
0	Clock division circuit operation stopped. BUZ fixed to low level.
1	Clock division circuit operation enabled. BUZ output enabled.

BCS1	BCS0		BUZ output clock selection	
			$f_{PRS} = 10 \text{ MHz}$	$f_{PRS} = 20 \text{ MHz}$
0	0	$f_{PRS}/2^{10}$	9.77 kHz	19.54 kHz
0	1	$f_{PRS}/2^{11}$	4.88 kHz	9.77 kHz
1	0	$f_{PRS}/2^{12}$	2.44 kHz	4.88 kHz
1	1	$f_{PRS}/2^{13}$	1.22 kHz	2.44 kHz

CLOE	PCL output enable/disable specification
0	Clock division circuit operation stopped. PCL fixed to low level.
1	Clock division circuit operation enabled. PCL output enabled.

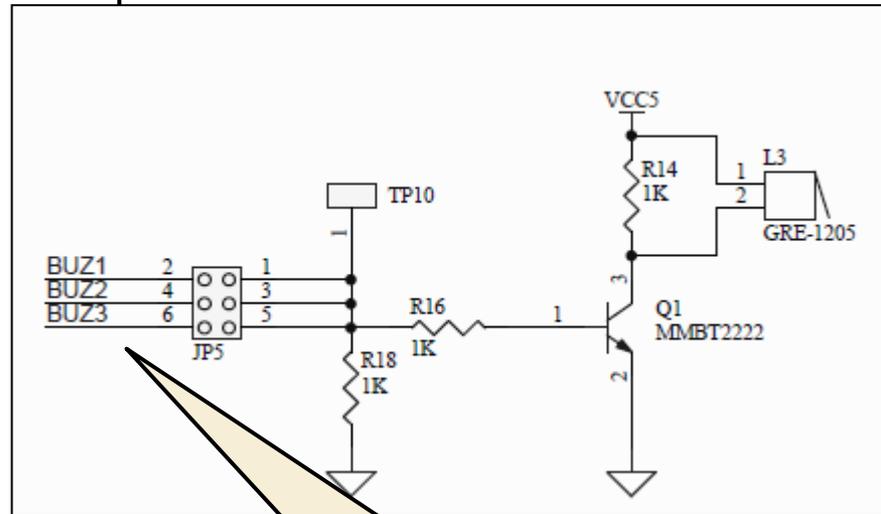
CCS3	CCS2	CCS1	CCS0		PCL output clock selection		
					$f_{SUB} = 32.768 \text{ kHz}$	$f_{PRS} = 10 \text{ MHz}$	$f_{PRS} = 20 \text{ MHz}$
0	0	0	0	$f_{PRS}^{\text{Note 1}}$	–	10 MHz	Setting prohibited <sup>Note 2</sup>
0	0	0	1	$f_{PRS}/2$	–	5 MHz	10 MHz
0	0	1	0	$f_{PRS}/2^2$	–	2.5 MHz	5 MHz
0	0	1	1	$f_{PRS}/2^3$	–	1.25 MHz	2.5 MHz
0	1	0	0	$f_{PRS}/2^4$	–	625 kHz	1.25 MHz
0	1	0	1	$f_{PRS}/2^5$	–	312.5 kHz	625 kHz
0	1	1	0	$f_{PRS}/2^6$	–	156.25 kHz	312.5 kHz
0	1	1	1	$f_{PRS}/2^7$	–	78.125 kHz	156.25 kHz
1	0	0	0	$f_{SUB}$	32.768 kHz	–	–
Other than above					Setting prohibited		

# EVM buzzer 회로 & Code

```
void main(void)
{
    //port setup
    PM14.1 = 0; //output
    PM2.4 = 1; //input for slide

    //주파수 결정
    CKS = 0b01100000;

    while(1) {
        if(P2.4)
            BZOE = 1;
        else
            BZOE = 0;
    }
}
```



- BUZ1 = BUZ/P141
- BUZ2 = P144
- BUZ3 = P120

# 16-bit Timer/Event counter overview

- ▶ 2개 내장: 00/01
- ▶ Functions
  - ▶ Interval timer
  - ▶ Square-wave output
  - ▶ External event counter
  - ▶ One-shot pulse output
  - ▶ PPG output (PWM like)
  - ▶ Pulse width measurement

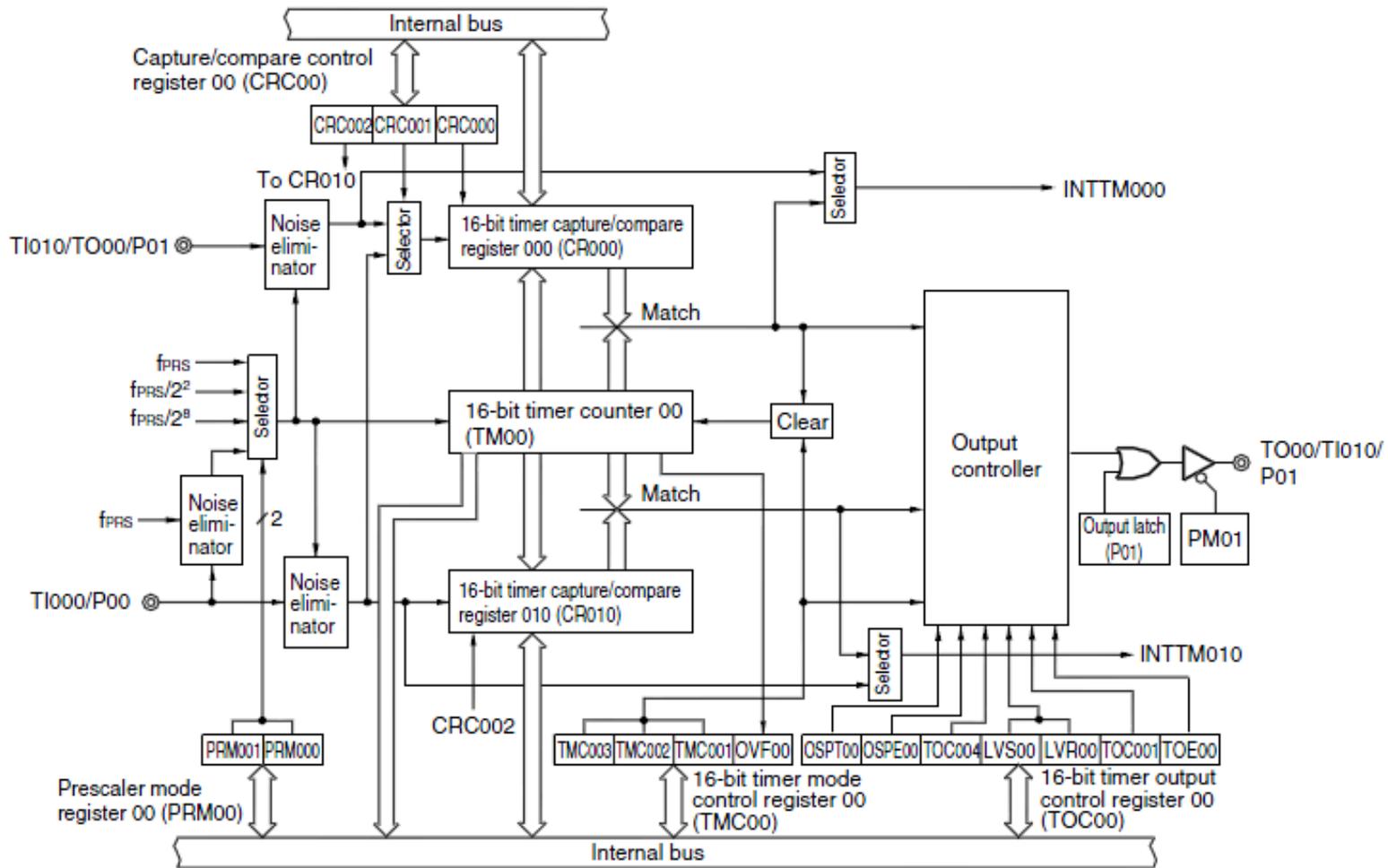
Table 7-1. Configuration of 16-Bit Timer/Event Counters 00 and 01

Item	Configuration
Time/counter	16-bit timer counter 0n (TM0n)
Register	16-bit timer capture/compare registers 00n, 01n (CR00n, CR01n)
Timer input	TI00n, TI01n pins
Timer output	TO0n pin, output controller
Control registers	16-bit timer mode control register 0n (TMC0n) 16-bit timer capture/compare control register 0n (CRC0n) 16-bit timer output control register 0n (TOC0n) Prescaler mode register 0n (PRM0n) Port mode register 0 (PM0) Port register 0 (P0)

Remark n = 0, 1

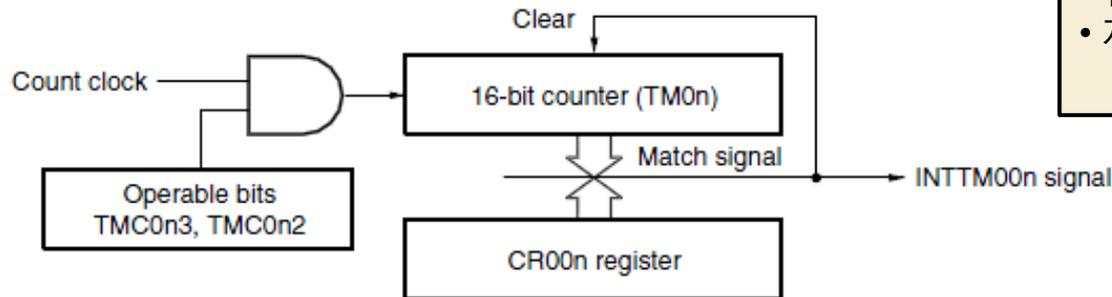
# Block diagram

Figure 7-1. Block Diagram of 16-Bit Timer/Event Counter 00



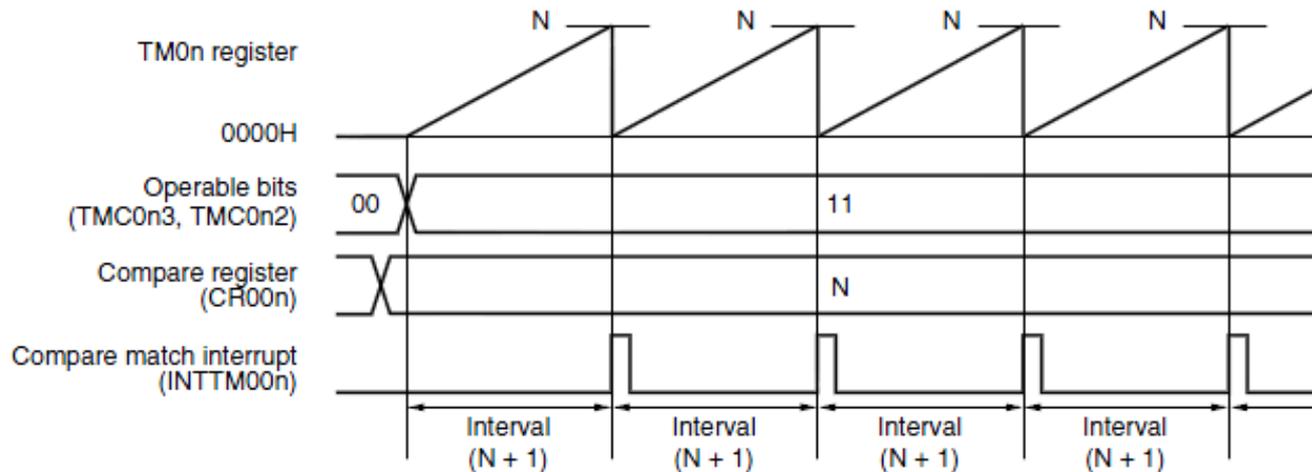
# Interval timer operation

Figure 7-16. Block Diagram of Interval Timer Operation



- 일정시간 마다 인터럽트 발생
- 일정시간 설정은 CR00n reg.
- 자동으로 TMon clear됨.

Figure 7-17. Basic Timing Example of Interval Timer Operation



# Square-wave output operation

Figure 7-20. Block Diagram of Square-Wave Output Operation

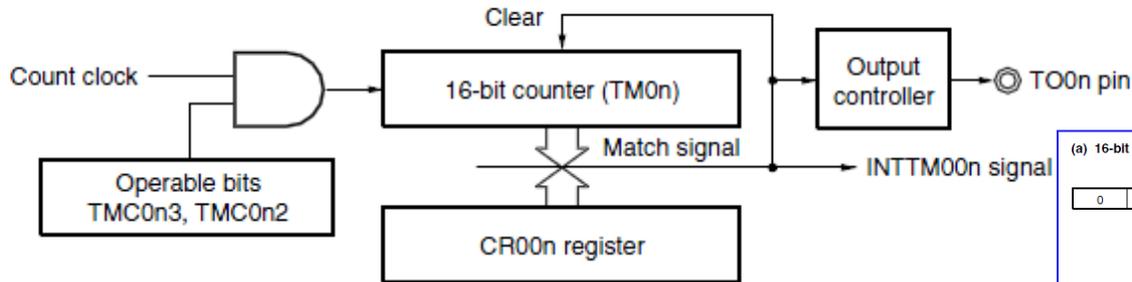
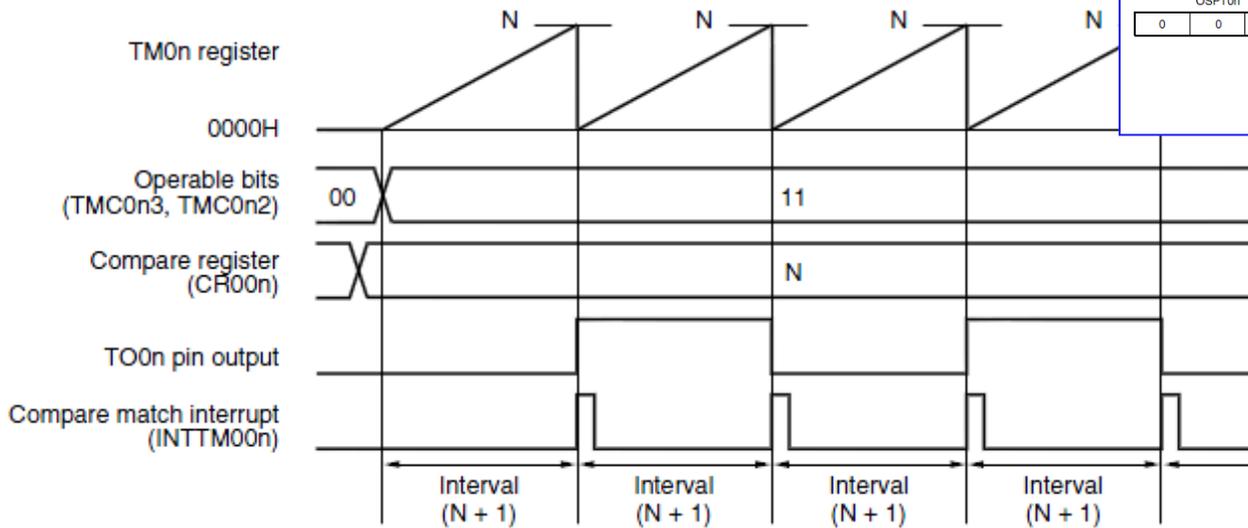


Figure 7-21. Basic Timing Example of Square-Wave Output Operation



(a) 16-bit timer mode control register 0n (TMC0n)

0	0	0	0	0	1	1	0	0
					TMC0n3	TMC0n2	TMC0n1	OVF0n

Clears and starts on match between TM0n and CR00n.

(b) Capture/compare control register 0n (CRC0n)

					CRC0n2			CRC0n1	CRC0n0
0	0	0	0	0	0	0	0	0	

CR00n used as compare register

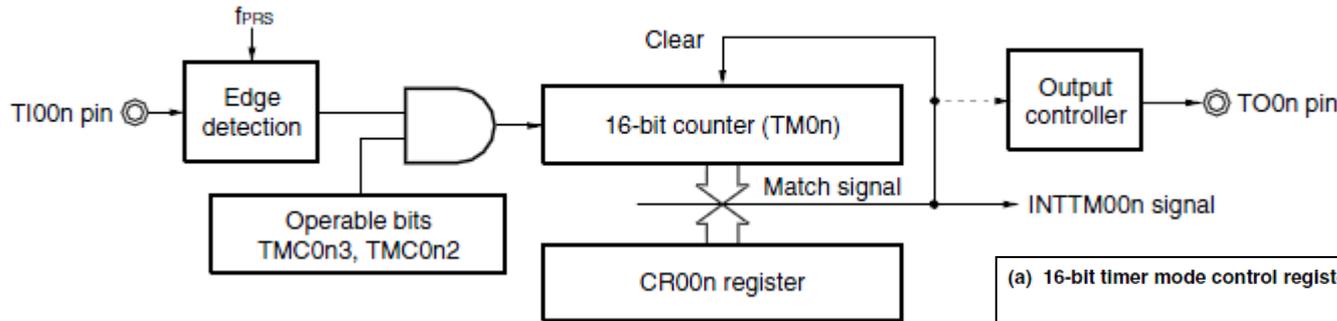
(c) 16-bit timer output control register 0n (TOC0n)

OSPT0n		OSPE0n	TOC0n4	TOC0n3	LVS0n	LVR0n	TOC0n1	TOE0n
0	0	0	0	0	0/1	0/1	1	1

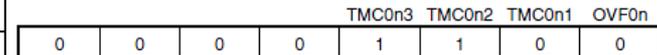
Enables TO0n pin output.  
Inverts TO0n pin output on match between TM0n and CR00n.  
Specifies initial value of TO0n output F/F

# External event counter

Figure 7-24. Block Diagram of External Event Counter Operation

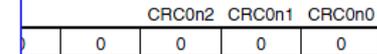


(a) 16-bit timer mode control register 0n (TMC0n)



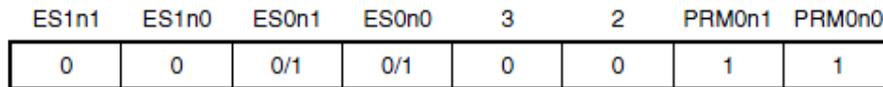
Clears and starts on match between TM0n and CR00n.

(b) Capture/compare control register 0n (CRC0n)



CR00n used as compare register

(d) Prescaler mode register 0n (PRM0n)



Selects count clock (specifies valid edge of TI00n).

- 00: Falling edge detection
- 01: Rising edge detection
- 10: Setting prohibited
- 11: Both edges detection

# Free-running timer operation 1

CR00n & CR01n → compare reg

Figure 7-37. Block Diagram of Free-Running Timer Mode  
(CR00n: Compare Register, CR01n: Compare Register)

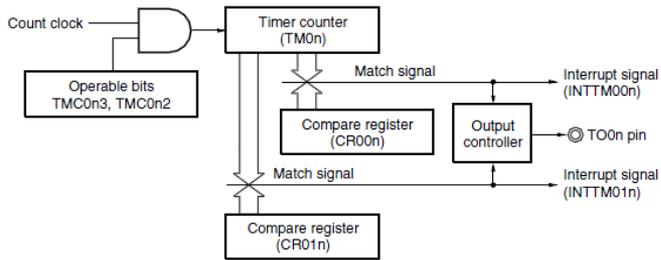
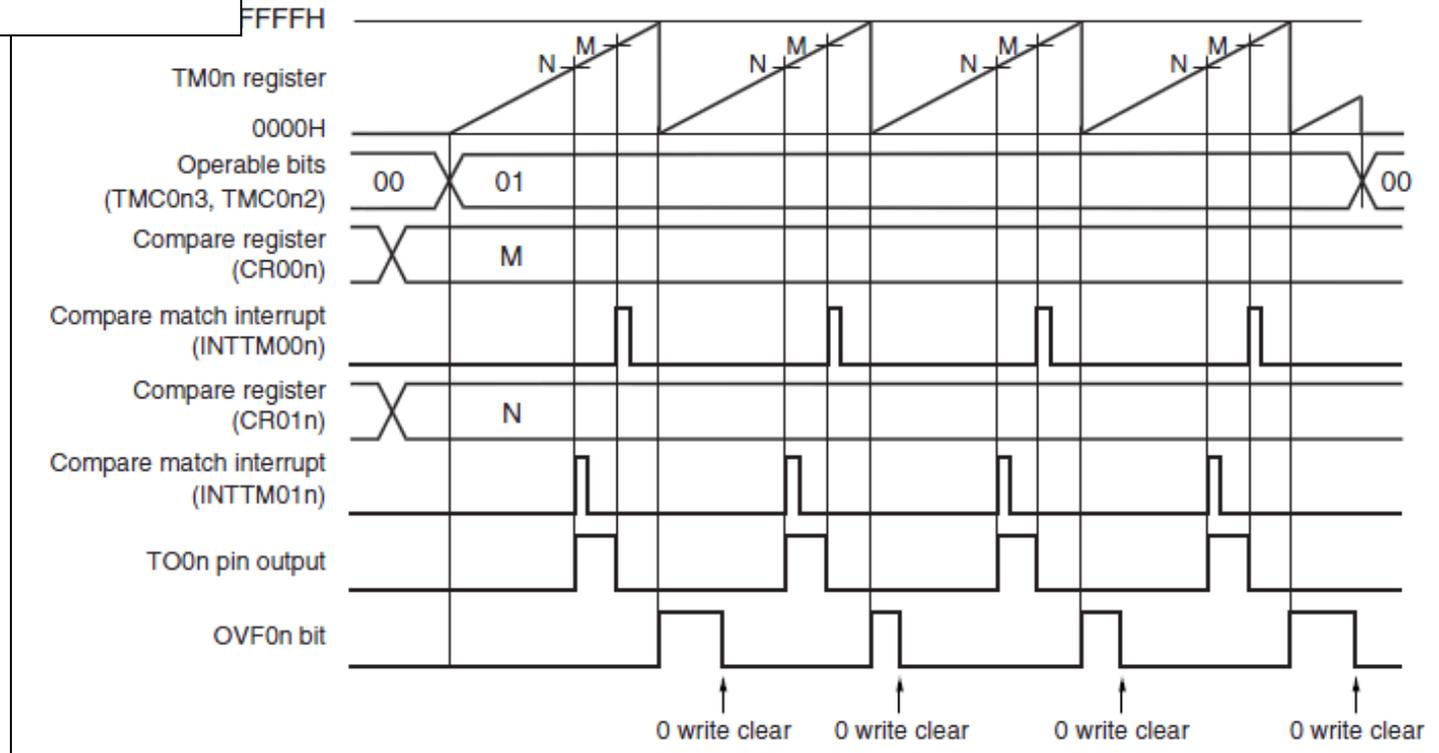


Figure 7-38. Timing Example of Free-Running Timer Mode  
(CR00n: Compare Register, CR01n: Compare Register)

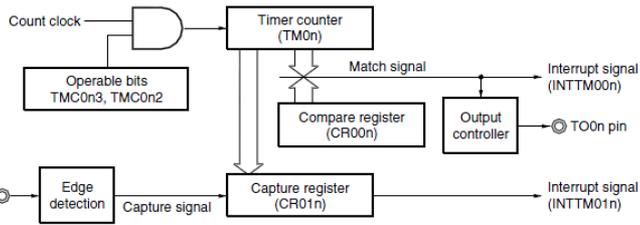
- TOC0n = 13H, PRM0n = 00H, CRC0n = 00H, TMC0n = 04H



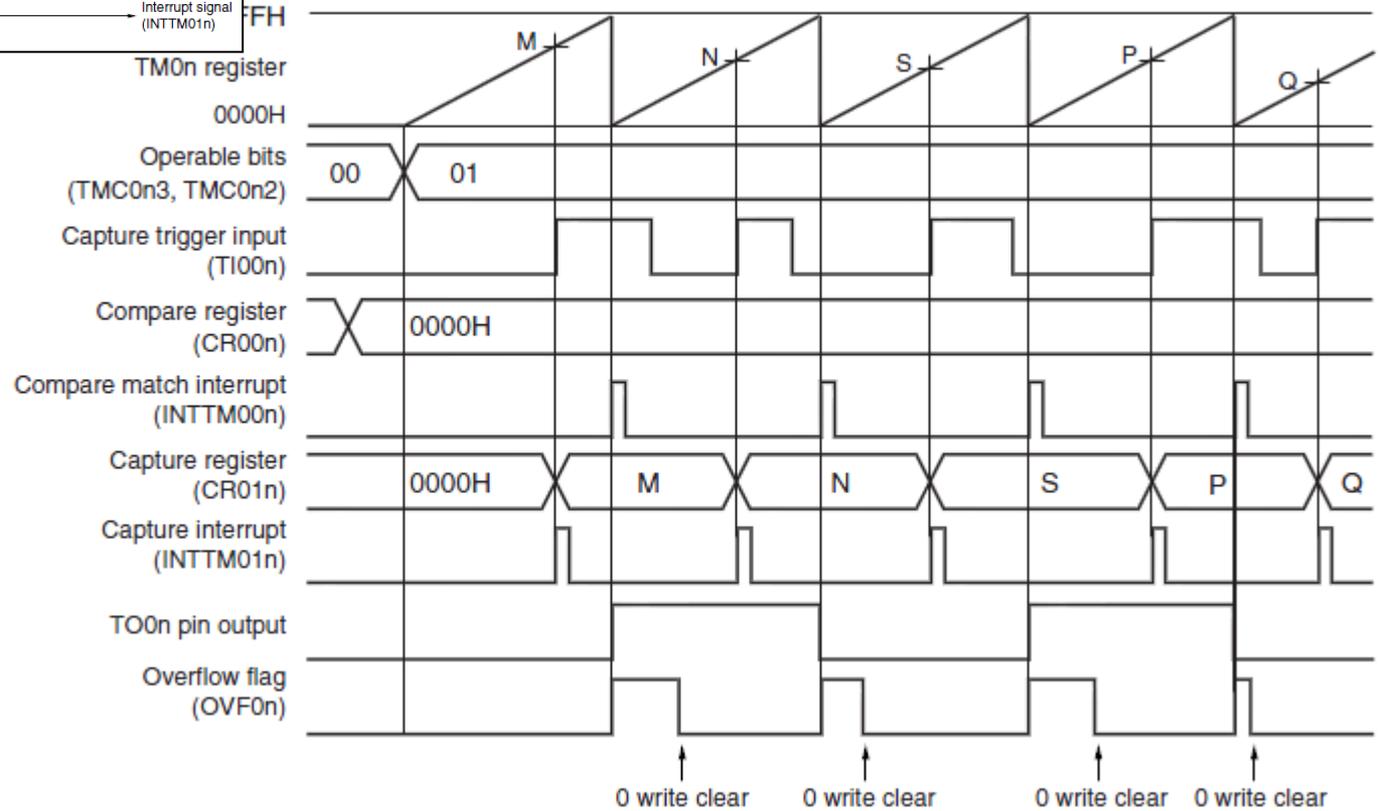
# Free-running timer operation 2

CR00n: compare, CR01n : capture

Figure 7-39. Block Diagram of Free-Running Timer Mode  
(CR00n: Compare Register, CR01n: Capture Register)



• TOC0n = 13H, PRM0n = 10H, CRC0n = 04H, TMC0n = 04H

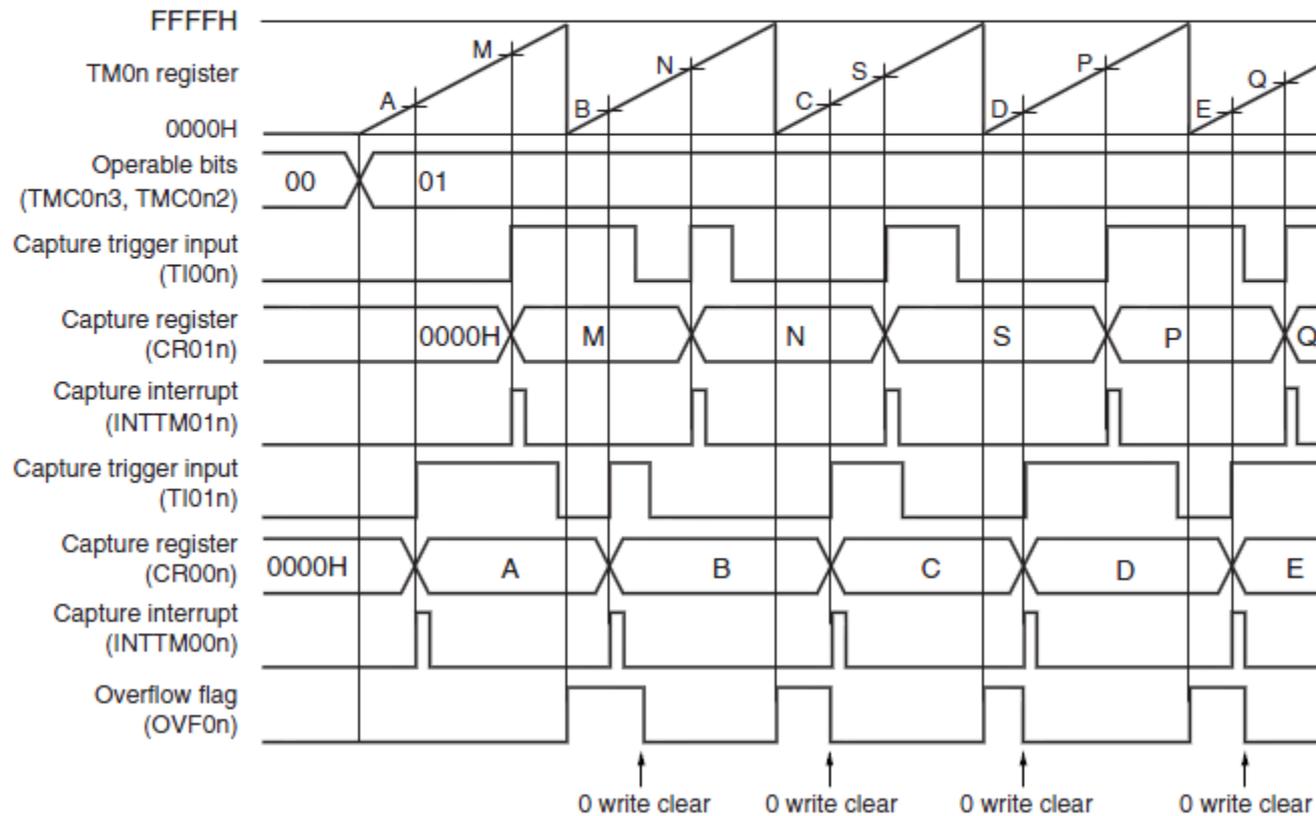


# Free-running timer operation 3

CR00n: capture, CR01n : capture

Figure 7-42. Timing Example of Free-Running Timer Mode  
(CR00n: Capture Register, CR01n: Capture Register) (1/2)

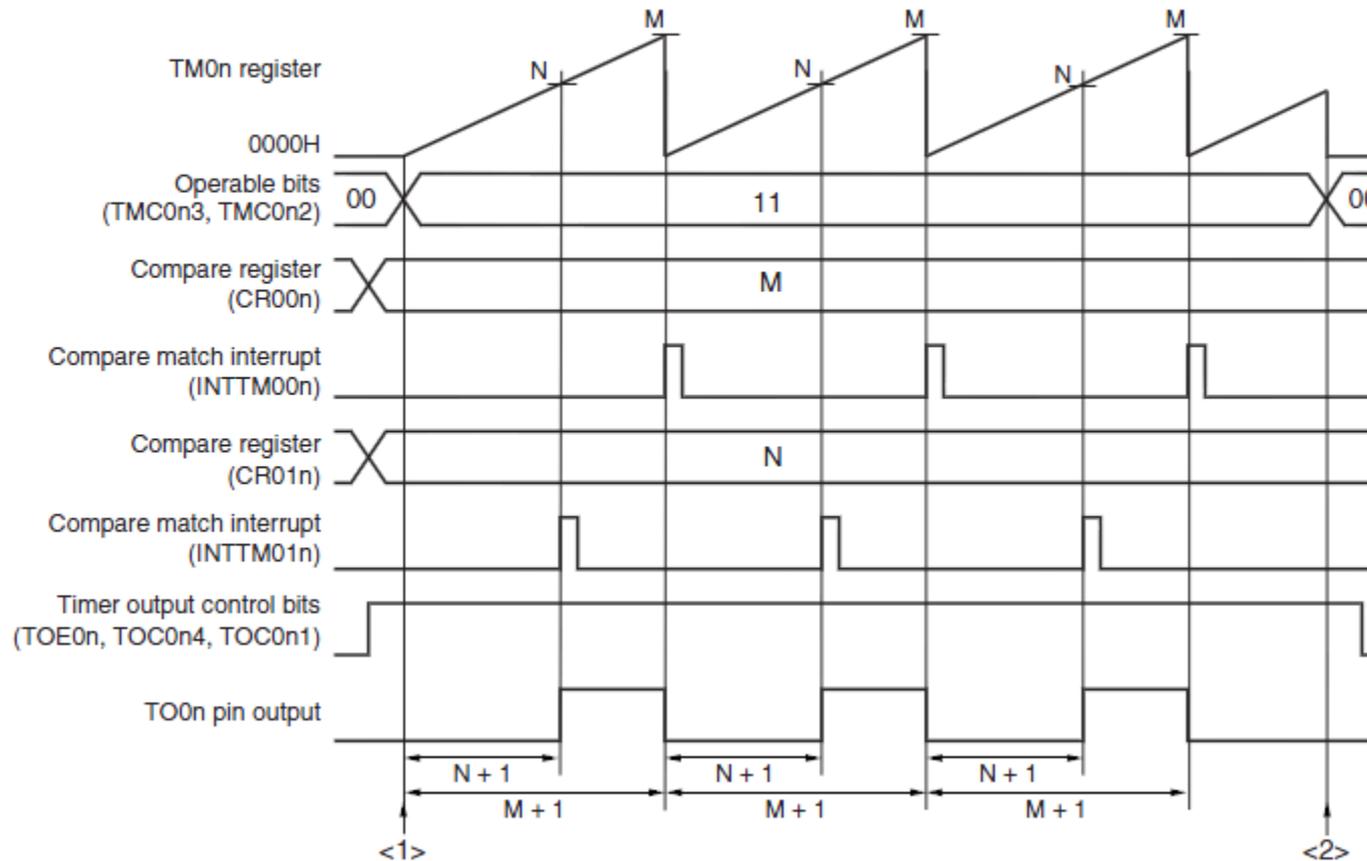
(a) TOC0n = 13H, PRM0n = 50H, CRC0n = 05H, TMC0n = 04H



# PPG output operation

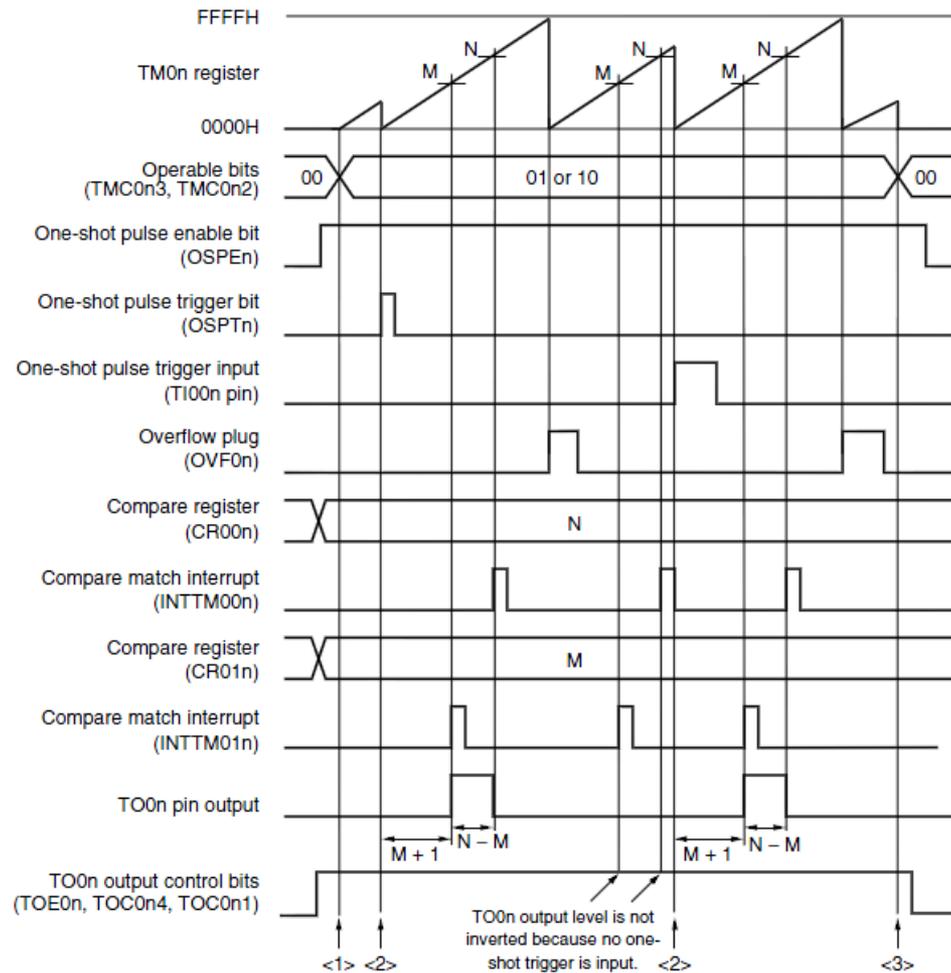
## ▶ PPG: Programmable Pulse Generation

Figure 7-47. Example of Software Processing for PPG Output Operation

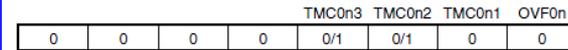


# One-shot pulse output operation

Figure 7-50. Example of Software Processing for One-Shot Pulse Output Operation (1/2)

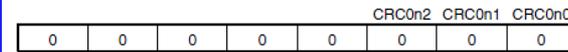


(a) 16-bit timer mode control register 0n (TMC0n)



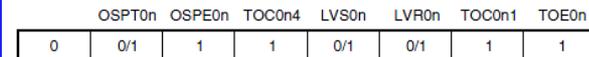
01: Free running timer mode  
10: Clear and start mode by valid edge of TI00n pin.

(b) Capture/compare control register 0n (CRC0n)



CR00n used as compare register  
CR01n used as compare register

(c) 16-bit timer output control register 0n (TOC0n)



Enables TO0n pin output  
Specifies initial value of TO0n pin output  
Inverts TO0n output on match between TM0n and CR00n/CR01n.  
Enables one-shot pulse output  
Software trigger is generated by writing 1 to this bit (operation is not affected even if 0 is written to it).

# Code for sounding using Tmr01

```
#pragma vect INTTM001 inttm001_isr
void main(void)
{
    //포트 설정 for T001
    PM6.0 = 0; //make output

    //TM01 설정
    PRM01 = 0x02; //setup freq.=fPRS/2^6 ==> 312.5KHz
    CRC01 = 0;
    TOC01 = 0x03; // enable T001 pin, invert match
    CR001 = 3125; //make 200Hz clock
    TMC01 = 0x0c;
    //interrupt setup
    TMMK001 = 0;
    EI(); //or DI();
    while(1);
}
__interrupt void inttm001_isr(void)
{
    LED0 ^= 1; //toggle LED0
}
```

TMR01의 출력(TO01/P0.6)이 간단한 OP amp.를 거쳐 스피커에 연결되어 있다. 이를 이용하여 간단하게 도/레/미를 연주한다.

- TMR 설정 순서
- Prescaler mode reg., Capture control reg., Output control reg., Timer control mode reg. (starting timer..)